

Diseño con microcontroladores

Entradas y salidas digitales: clase I

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Universidad Politécnica de Madrid

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Escuela Técnica Superior de
Ingenieros Informáticos



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DE MADRID

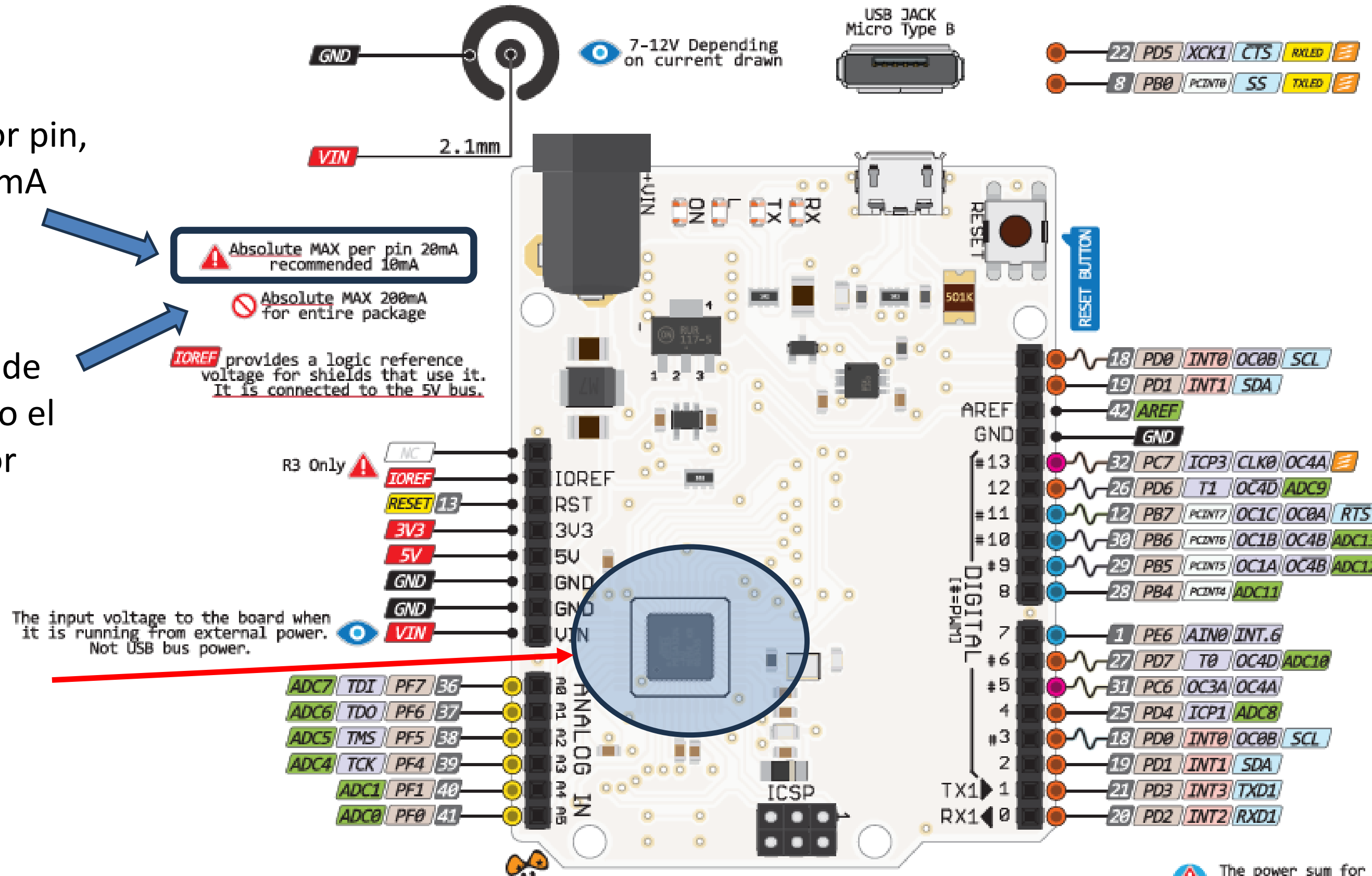
LEONARDO PINOUT



Máximo 20mA por pin,
recomendado 10mA

Máximo 200mA de
consumo en todo el
microcontrolador

Atmega 32U4



⚠ Absolute MAX per pin 20mA recommended 10mA
⊘ Absolute MAX 200mA for entire package
IOREF provides a logic reference voltage for shields that use it. It is connected to the 5V bus.

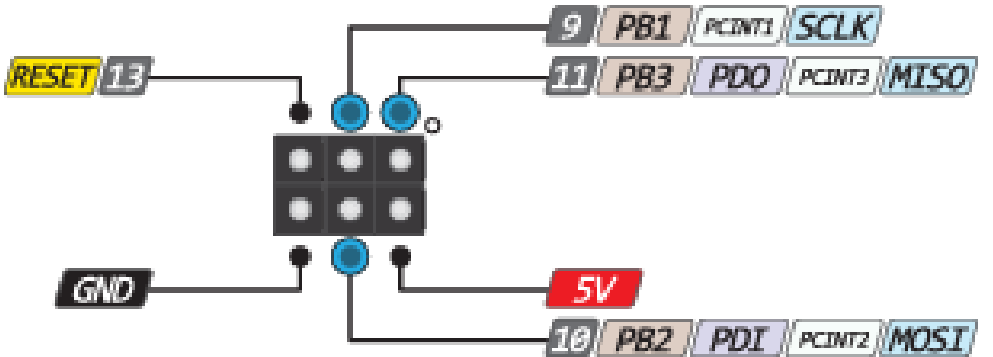
The input voltage to the board when it is running from external power. Not USB bus power.

- █ Power
- █ GND
- █ Serial Pin
- █ Analog Pin
- █ Control
- INT
- Physical Pin
- Port Pin
- Pin function
- Interrupt Pin
- ~ PWM Pin
- ● ● Port Power ⚠

⚠ The power sum for each pin's group should not exceed 100mA

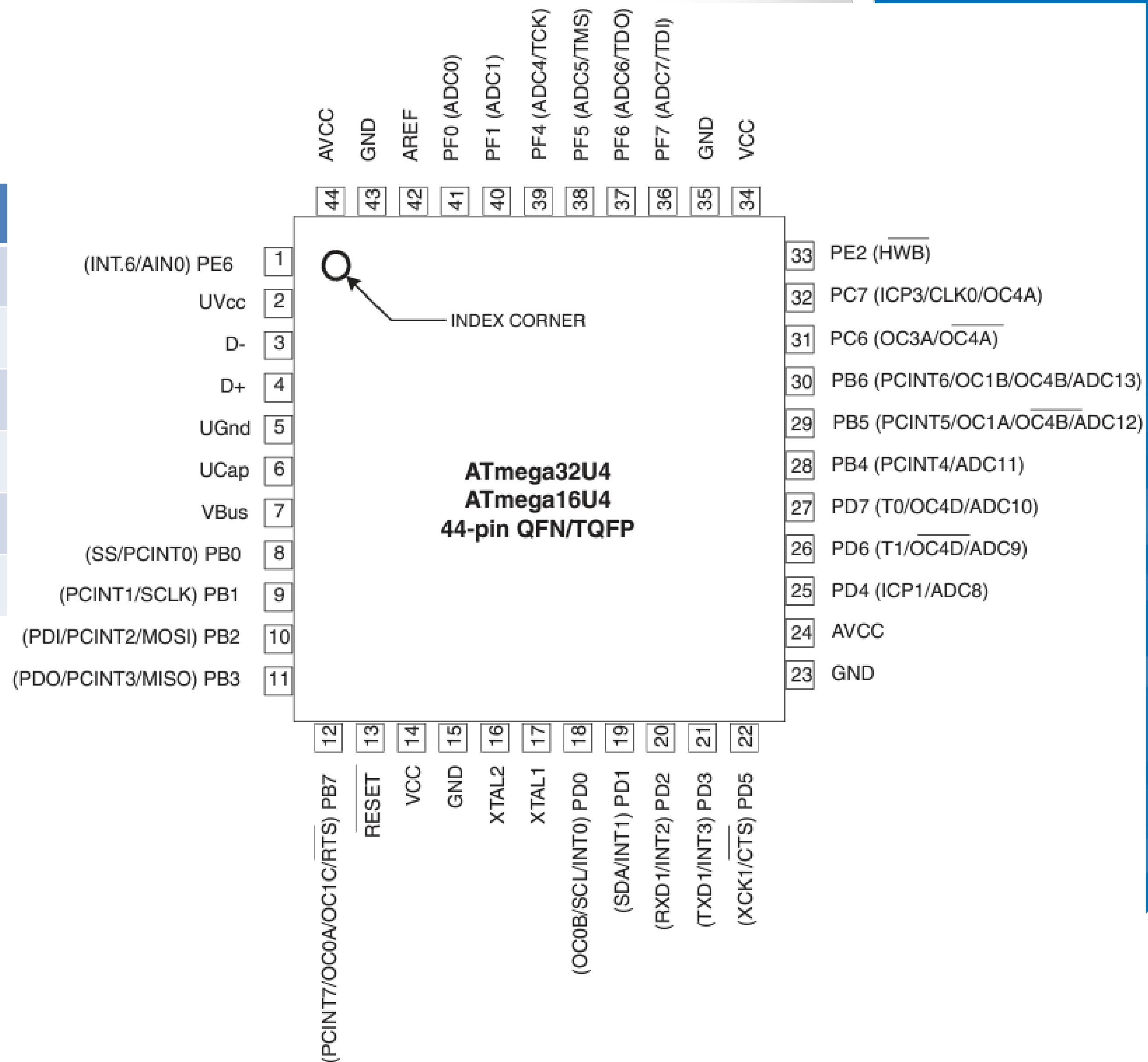
PWM TYPE

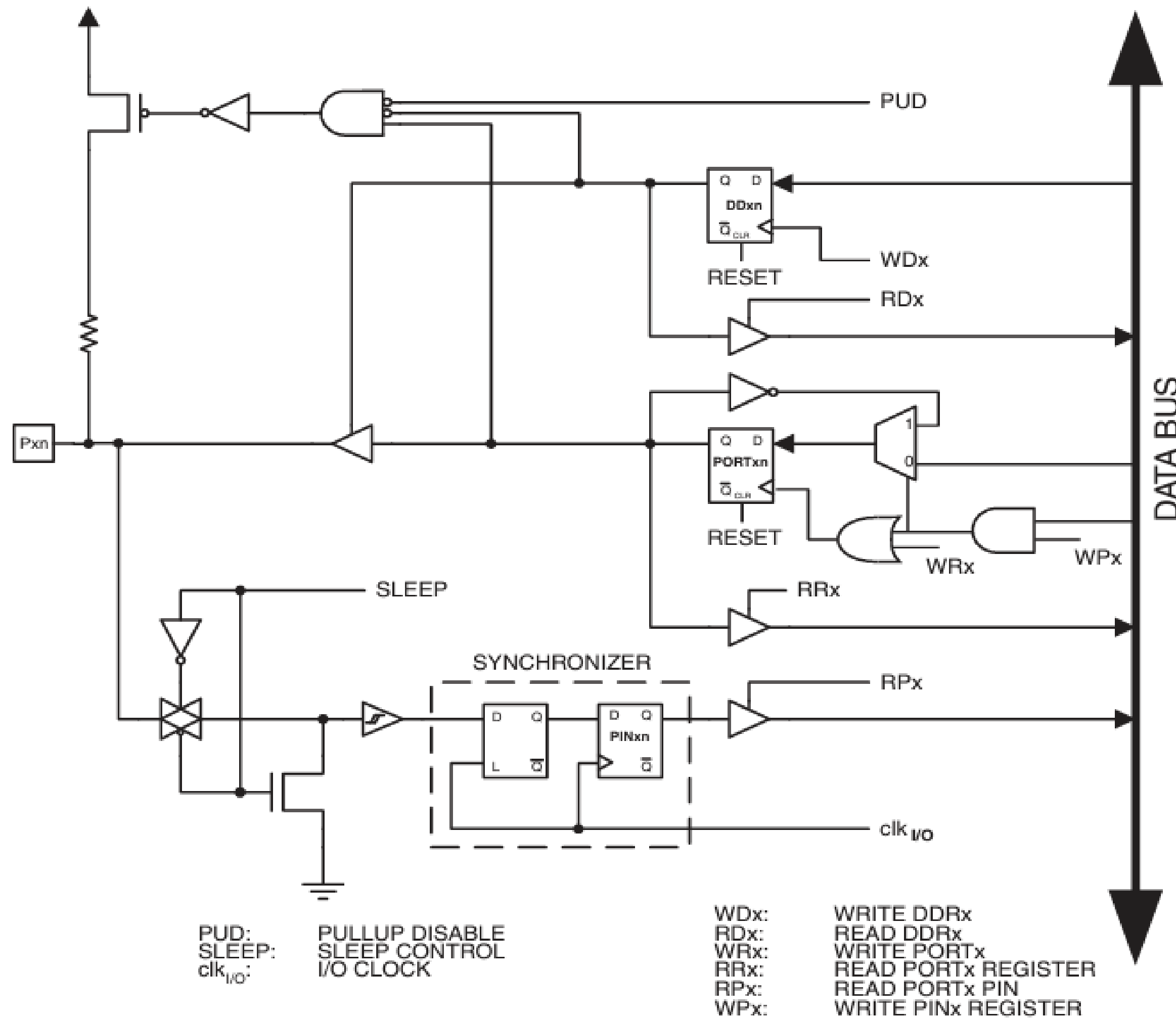
- ~ 10bit
- ~ 8/16bit
- ~ HS
- ~ 16bit
- ~ 8bit



Arduino	ATmega
D0	PD2
D1	PD3
D2	PD1
D3	PD0
D4	PD4
D5	PC6
D6	PD7
D7	PE6
D8	PB4
D9	PB5
D10	PB6
D11	PB7
D12	PD6
D13	PC7

Arduino	ATmega
A0	PF7
A1	PF6
A2	PF5
A3	PF4
A4	PF1
A5	PF0

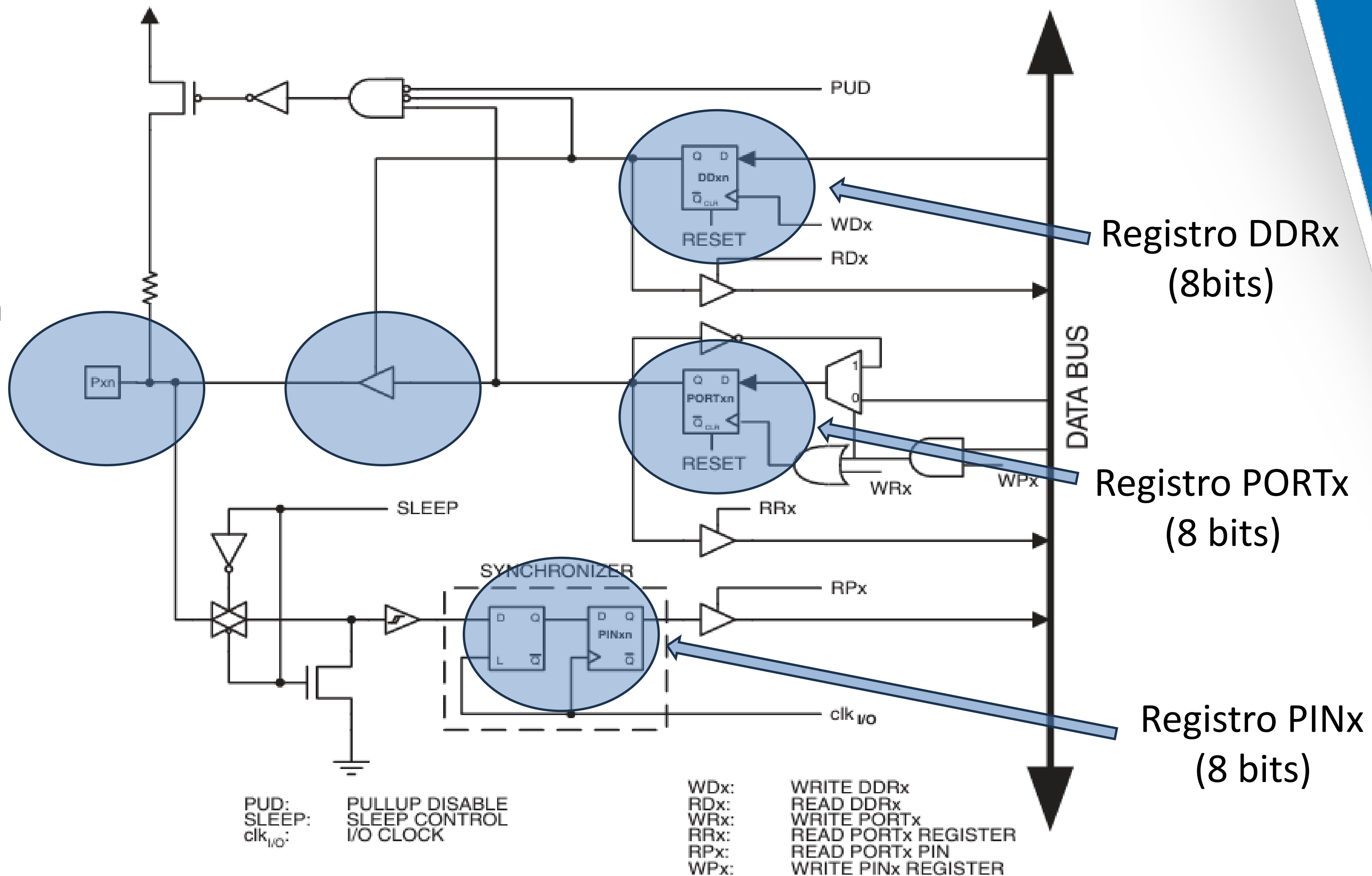




Note: 1. WRx, WPx, WDx, RRx, RPx, and RDx are common to all pins within the same port. clk_{I/O}, SLEEP, and PUD are common to all ports.



Salida física



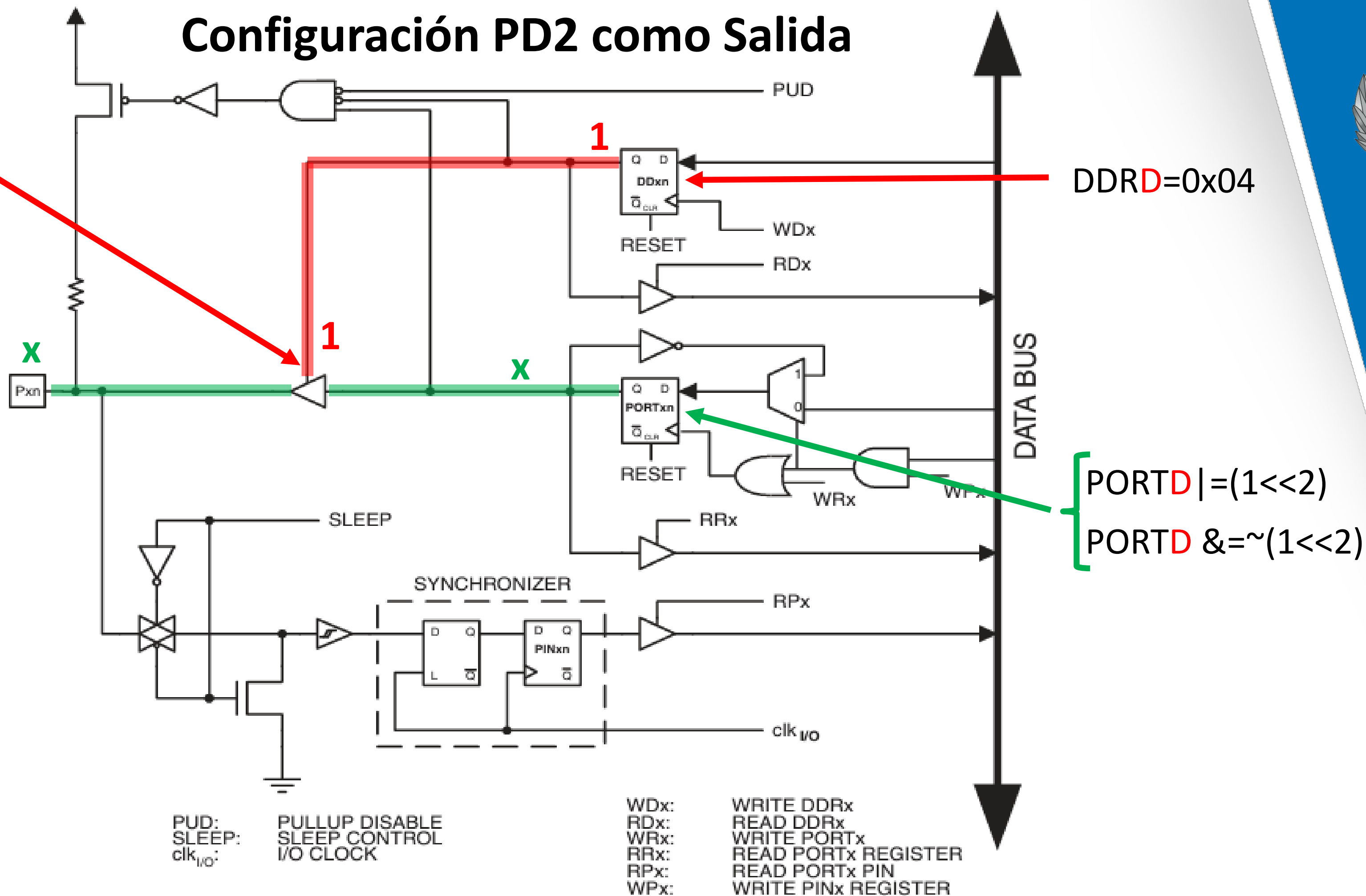
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Configuración PD2 como Salida

Activamos el driver triestado

Salida X=1 → 5V
X=0 → 0V

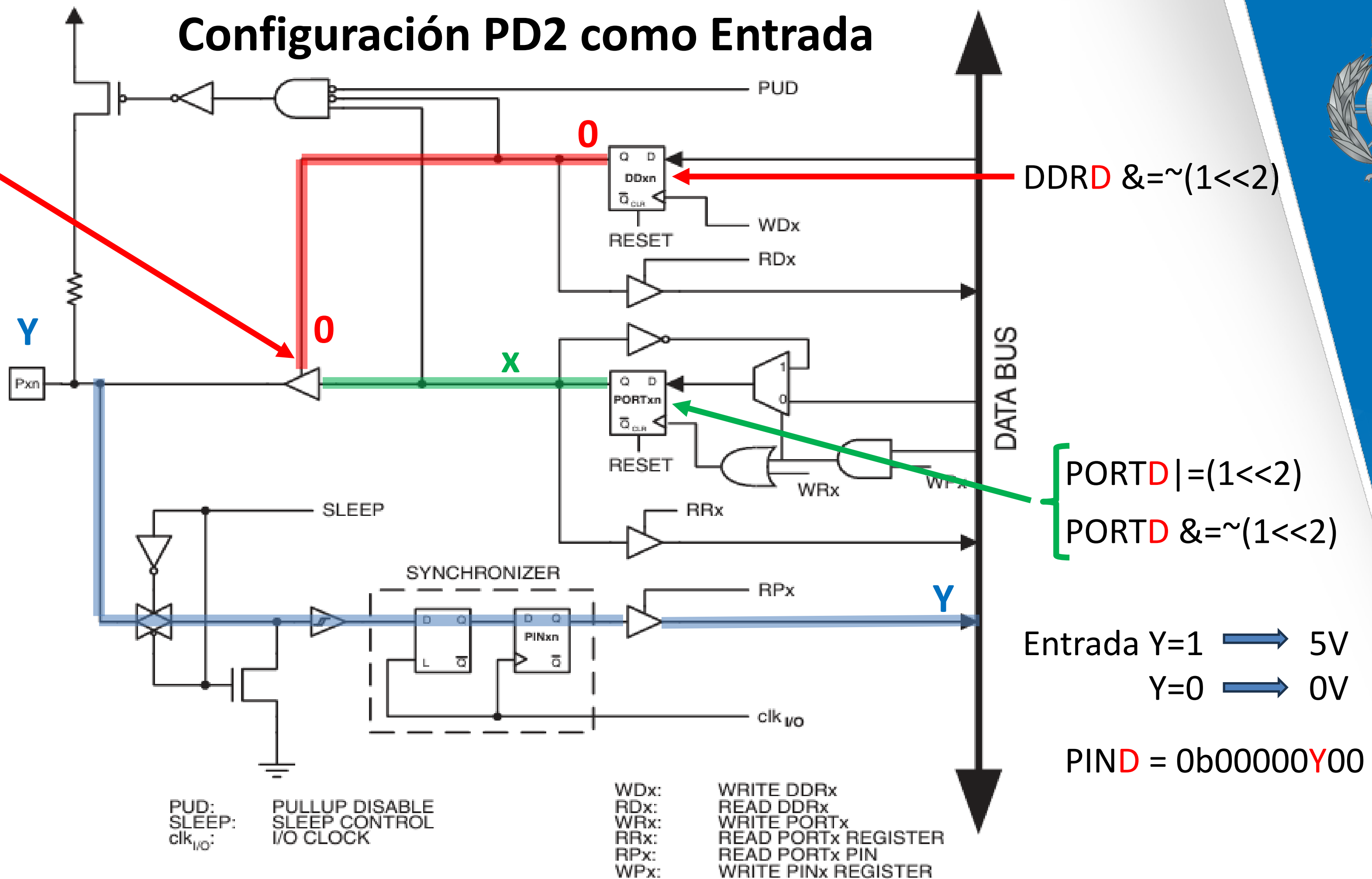


Note: 1. WRx, WPx, WDx, RRx, RPx, and RDx are common to all pins within the same port. clk_{I/O}, SLEEP, and PUD are common to all ports.



Configuración PD2 como Entrada

Desactivamos el driver triestado

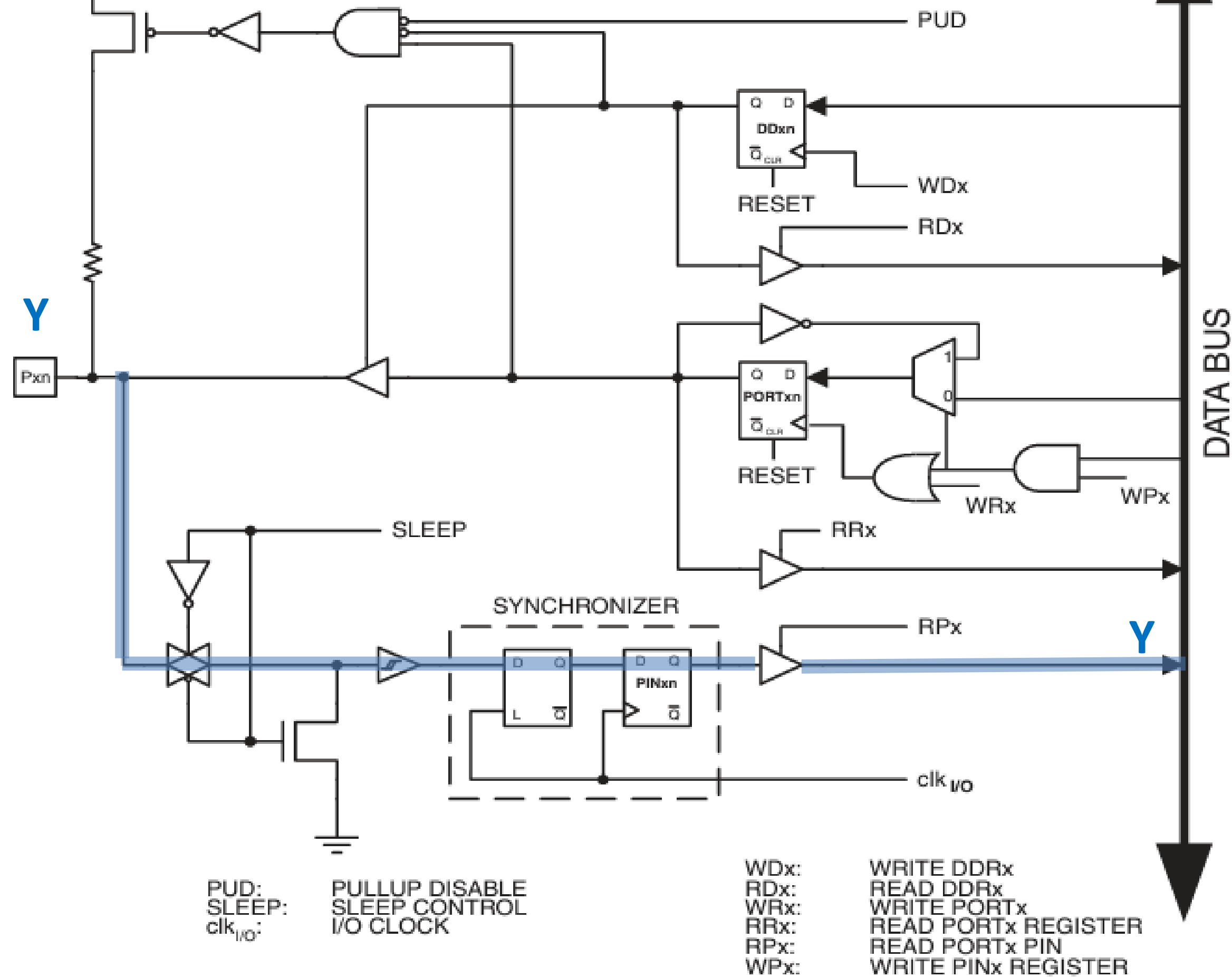


Note: 1. WRx, WPx, WDX, RRx, RPx, and RDx are common to all pins within the same port. clk_{I/O}, SLEEP, and PUD are common to all ports.



Configuración PD2 como Entrada

¿Qué valor tomaría **Y**, si no está conectado a ningún circuito?



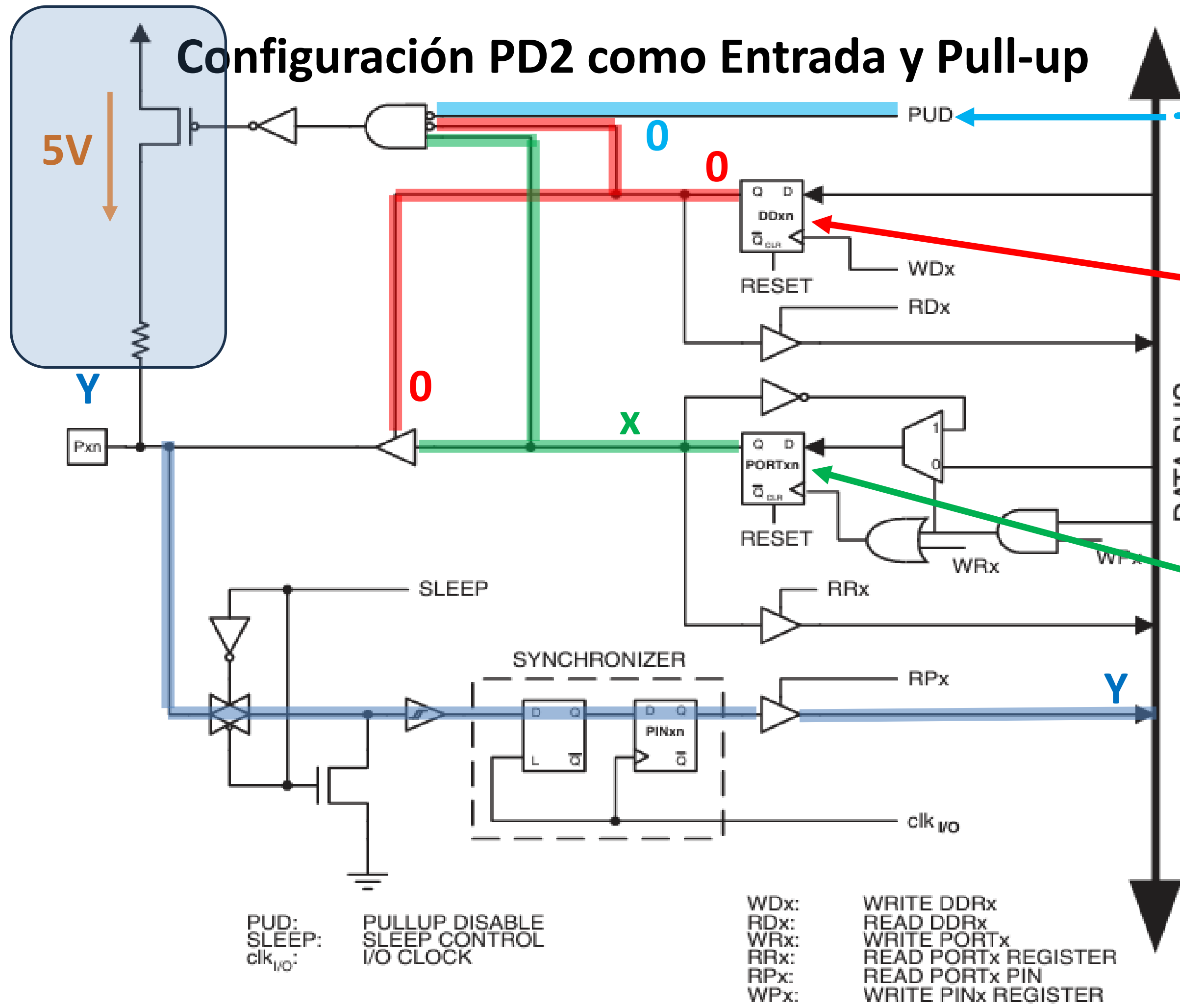
Entrada Y=1 → 5V
Y=0 → 0V

PIND = 0b00000**Y**00

Note: 1. WRx, WPx, WDx, RRx, RPx, and RDx are common to all pins within the same port. clk_{I/O}, SLEEP, and PUD are common to all ports.



Configuración PD2 como Entrada y Pull-up



MCU-Registro de control
 MCUCR $|=(1<<4)$ desactiva pull-up
 MCUCR $\&=\sim(1<<4)$ activa pull-up

$DDRD \&=\sim(1<<2)$

$PORTD |=(1<<2) \rightarrow ?$
 $PORTD \&=\sim(1<<2) \rightarrow ?$

Entrada $Y=1 \rightarrow 5V$
 $Y=0 \rightarrow 0V$

$PIND = 0b00000Y00$

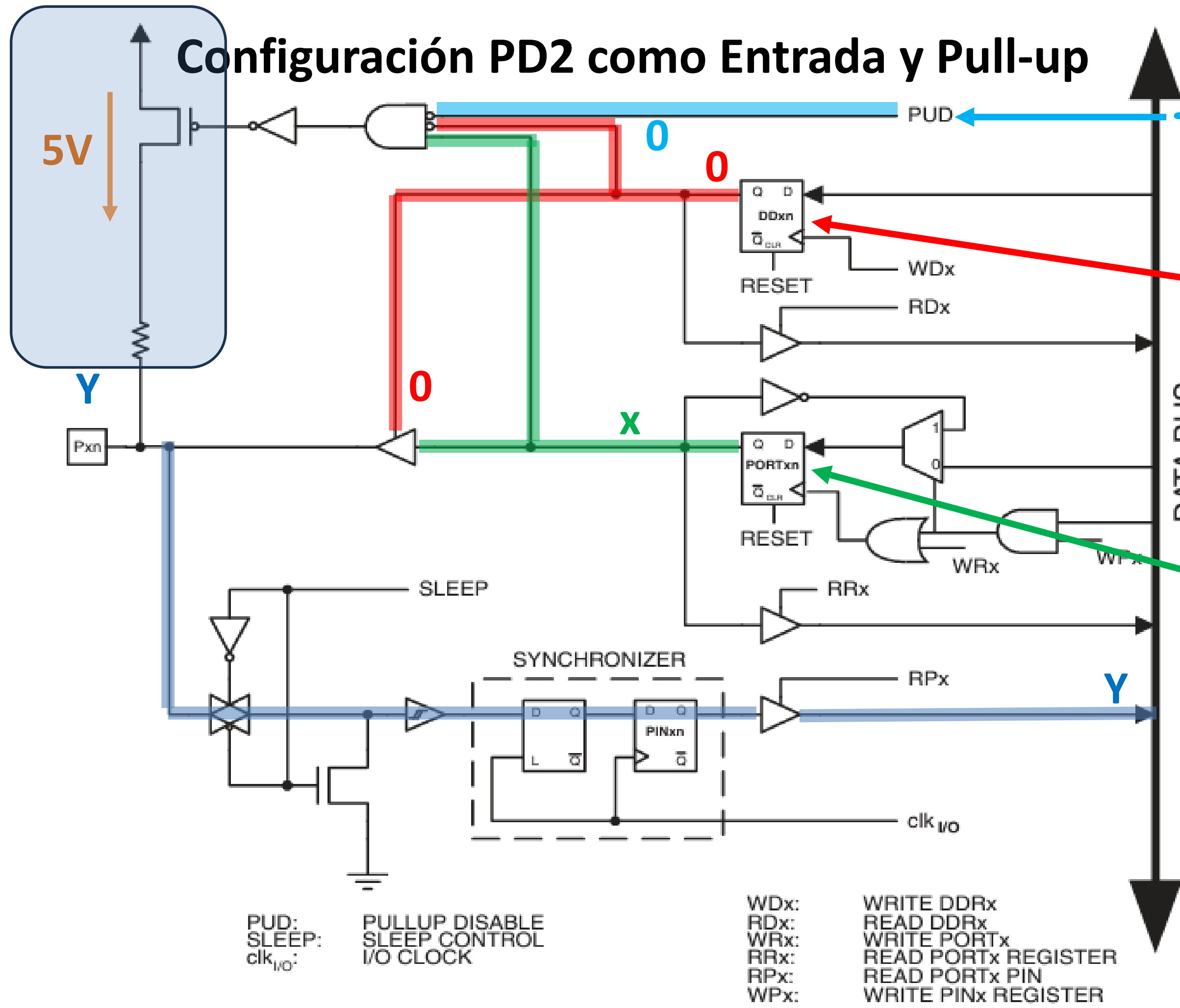
PUD: PULLUP DISABLE
 SLEEP: SLEEP CONTROL
 $clk_{I/O}$: I/O CLOCK

WDx: WRITE DDRx
 RDx: READ DDRx
 WRx: WRITE PORTx
 RRx: READ PORTx REGISTER
 RPx: READ PORTx PIN
 WPx: WRITE PINx REGISTER

Note: 1. WRx, WPx, WDx, RRx, RPx, and RDx are common to all pins within the same port. $clk_{I/O}$, SLEEP, and PUD are common to all ports.



Configuración PD2 como Entrada y Pull-up



MCU-Registro de control
 MCUCR $|=(1<<4)$ desactiva pull-up
 MCUCR $\&=\sim(1<<4)$ activa pull-up

$DDRD \&=\sim(1<<2)$

$PORTD |=(1<<2)$ → Activa
 $PORTD \&=\sim(1<<2)$ → Desactiva

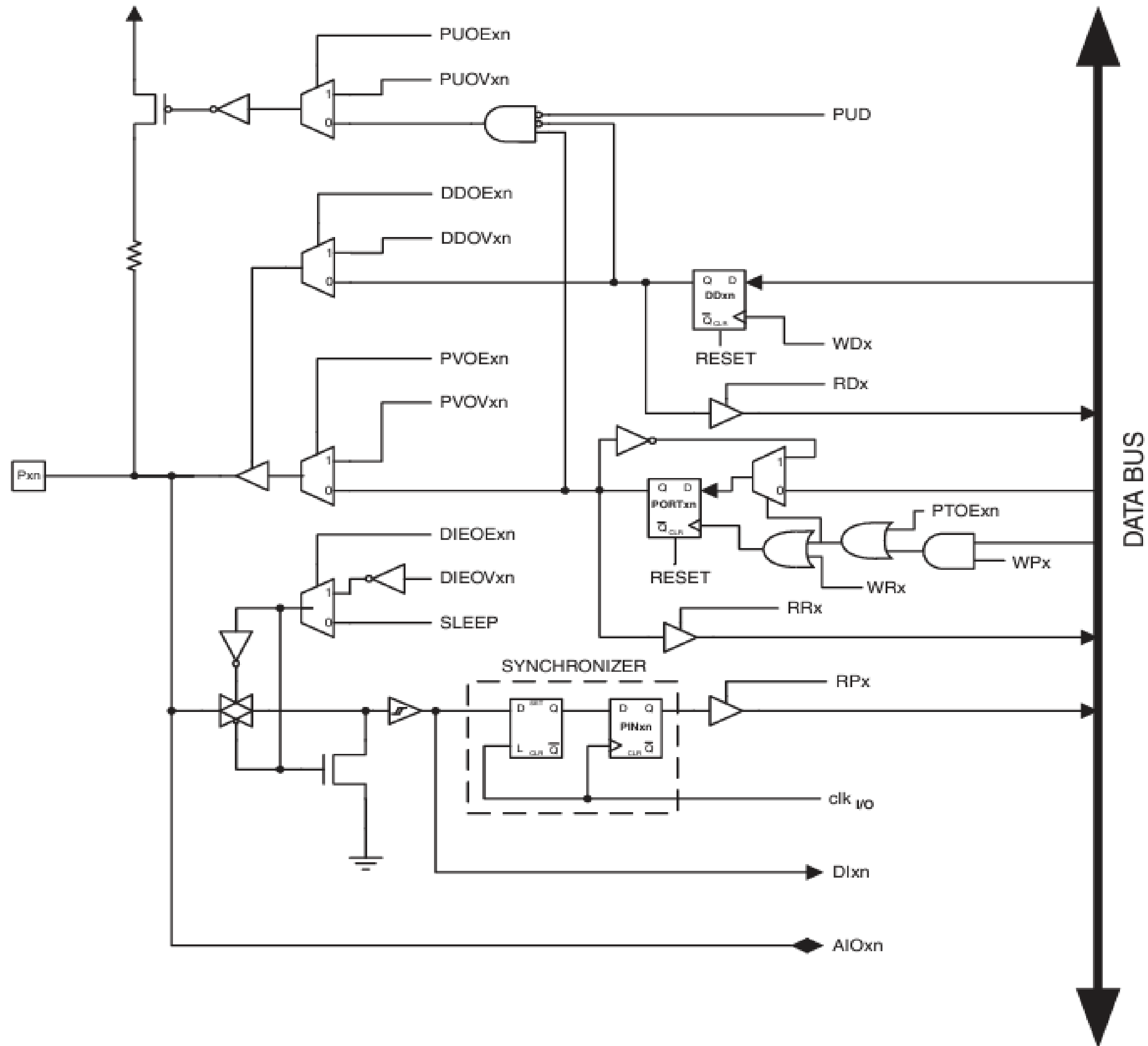
Entrada $Y=1$ → 5V
 $Y=0$ → 0V

$PIND = 0b00000Y00$

PUD: PULLUP DISABLE
 SLEEP: SLEEP CONTROL
 $clk_{I/O}$: I/O CLOCK

WDx: WRITE DDRx
 RDx: READ DDRx
 WRx: WRITE PORTx
 RRx: READ PORTx REGISTER
 RPx: READ PORTx PIN
 WPx: WRITE PINx REGISTER

Note: 1. WRx, WPx, WDx, RRx, RPx, and RDx are common to all pins within the same port. $clk_{I/O}$, SLEEP, and PUD are common to all ports.





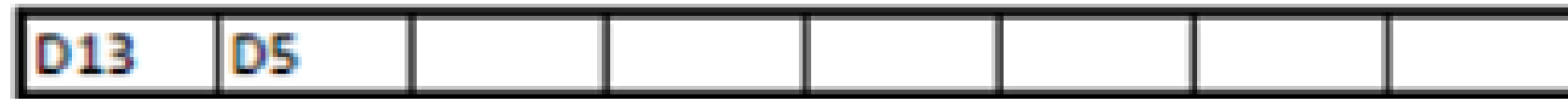
Arduino	ATmega
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D5	PC6
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D11	PB7
D12	PD6
D13	PC7

Arduino	ATmega
A0	PF7
A1	PF6
A2	PF5
A3	PF4
A4	PF1
A5	PF0

PORTB



PORTC



PORTD



PORTE



AIN0

PORTF



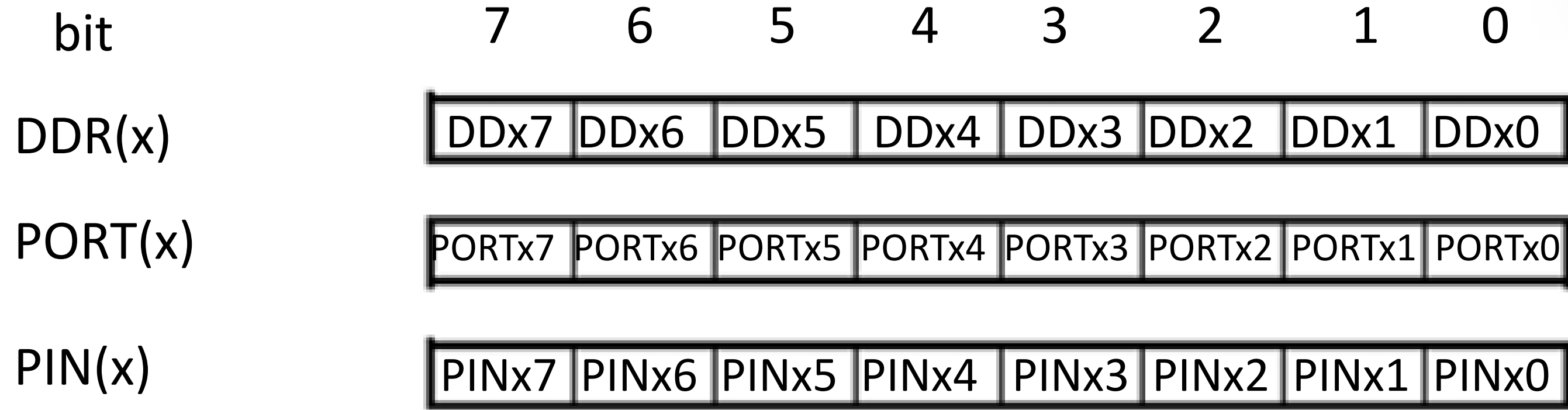
ADC7 ADC6 ADC5 ADC4

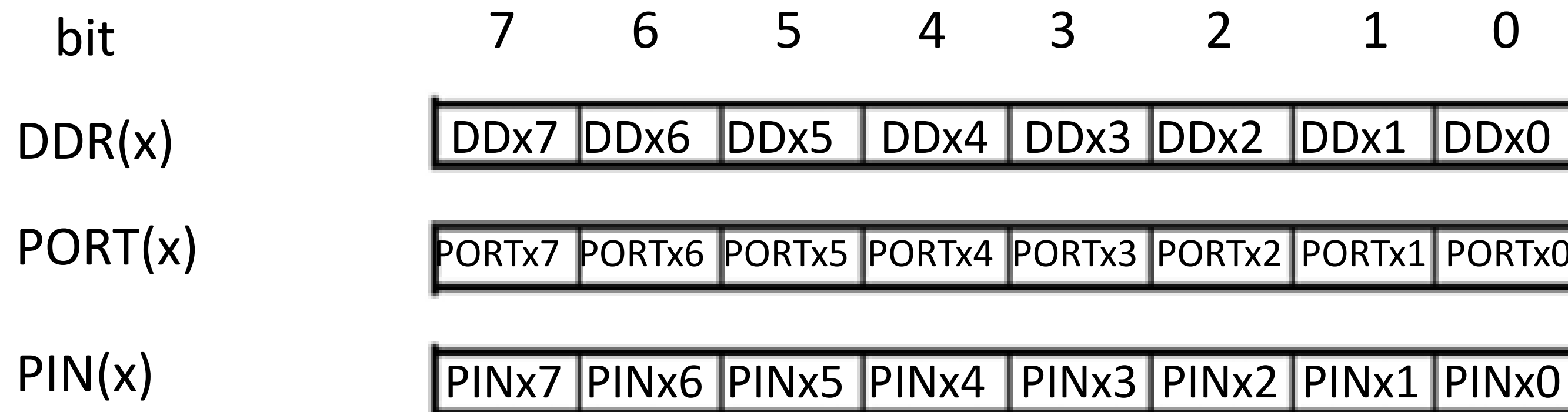
ADC1 ADC0



Arduino	ATmega
D0	PD2
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D6	PD7
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D11	PB7
D12	PD6
D13	PC7

Arduino	ATmega
A0	PF7
A1	PF6
A2	PF5
A3	PF4
A4	PF1
A5	PF0





¿Cuál es la mejor?

Arduino

```
pinMode(pin, OUTPUT)
pinMode(pin, INPUT)
pinMode(pin, INPUT_PULLUP)

digitalWrite(pin, LOW)
digitalWrite(pin, HIGH)

Val=digitalRead(pin)
```

ATmega

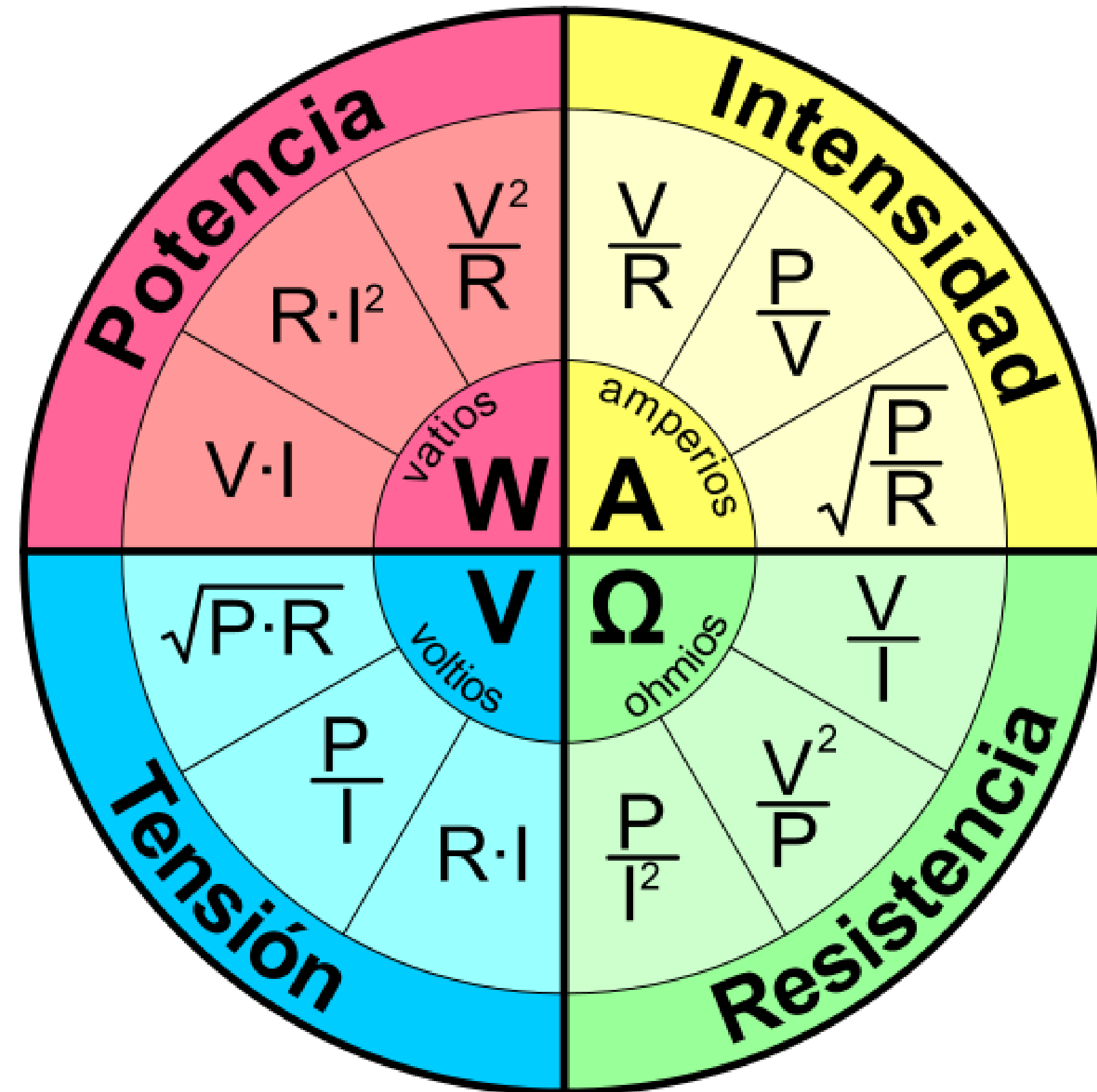
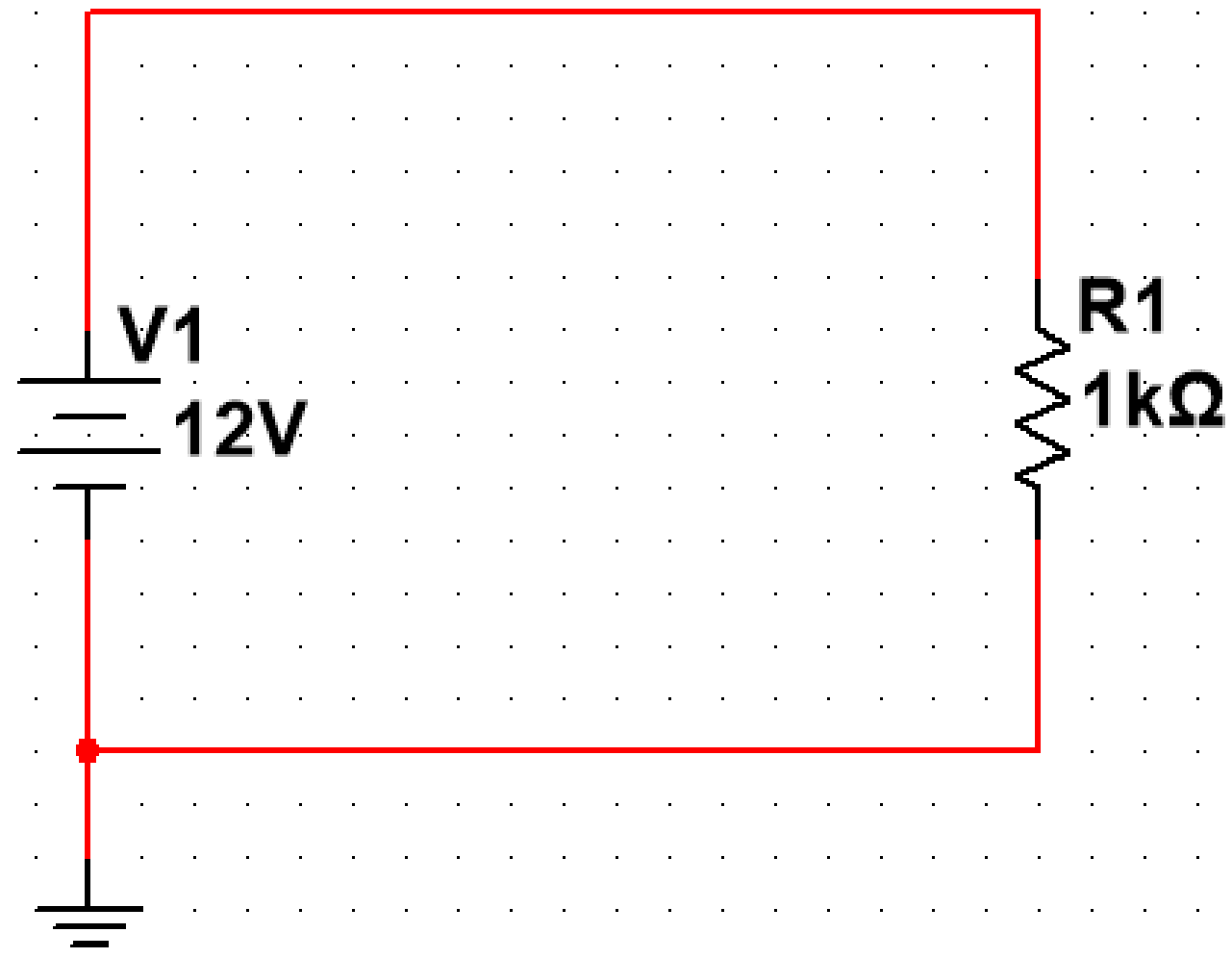
```
DDRB |=(1<<bit);
DDRB &=~(1<<bit);

PORTB |=(1<<bit);
PORTB &=~(1<<bit);

Val=PINB & (1<<pin)
```

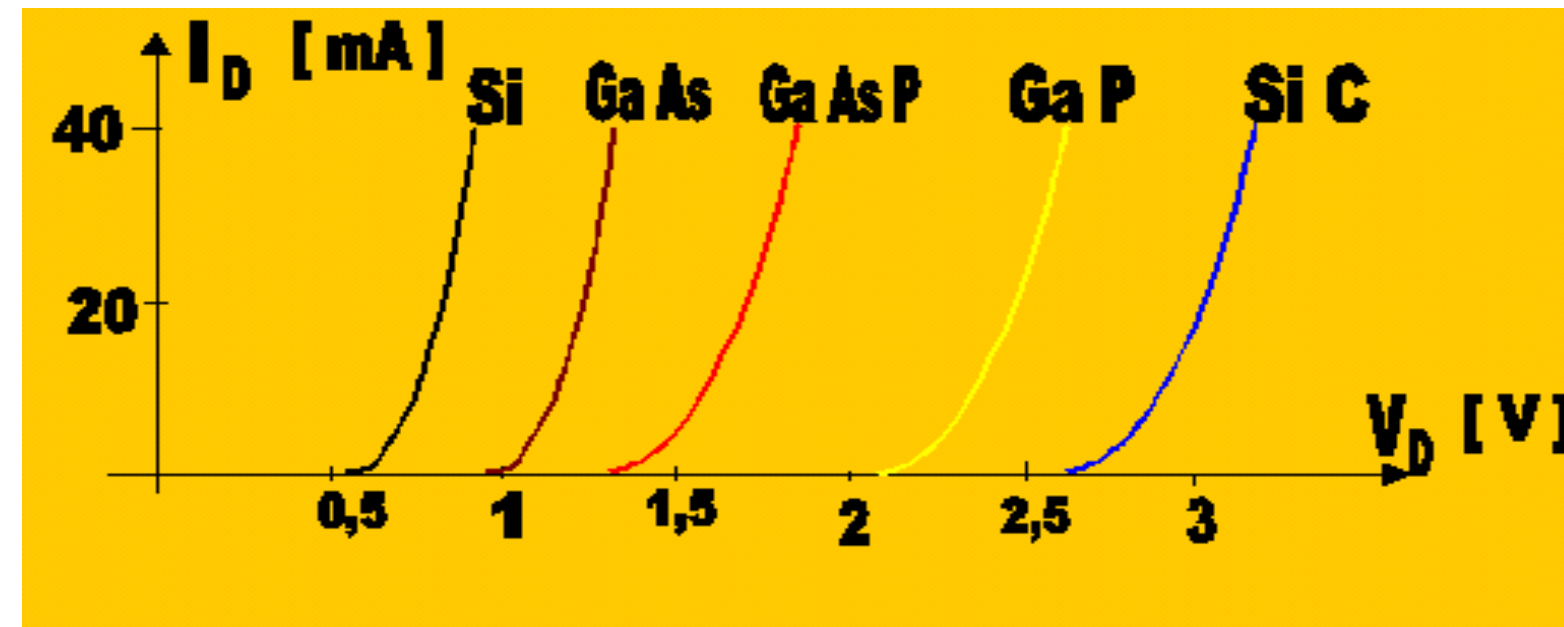
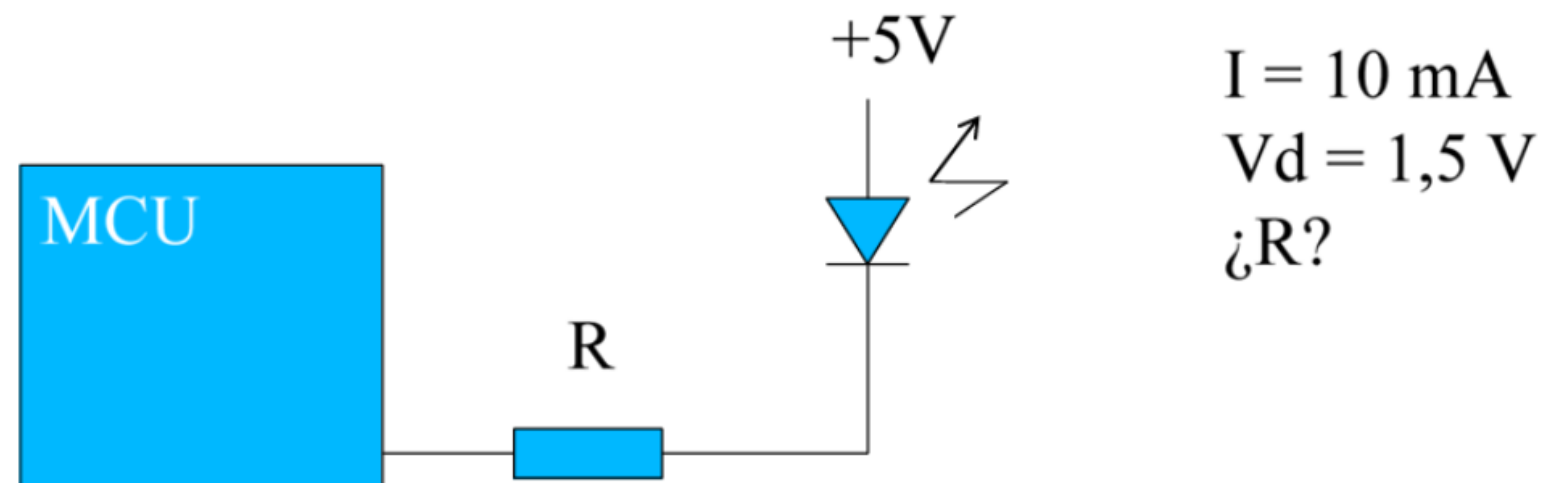


LEY DE OHM

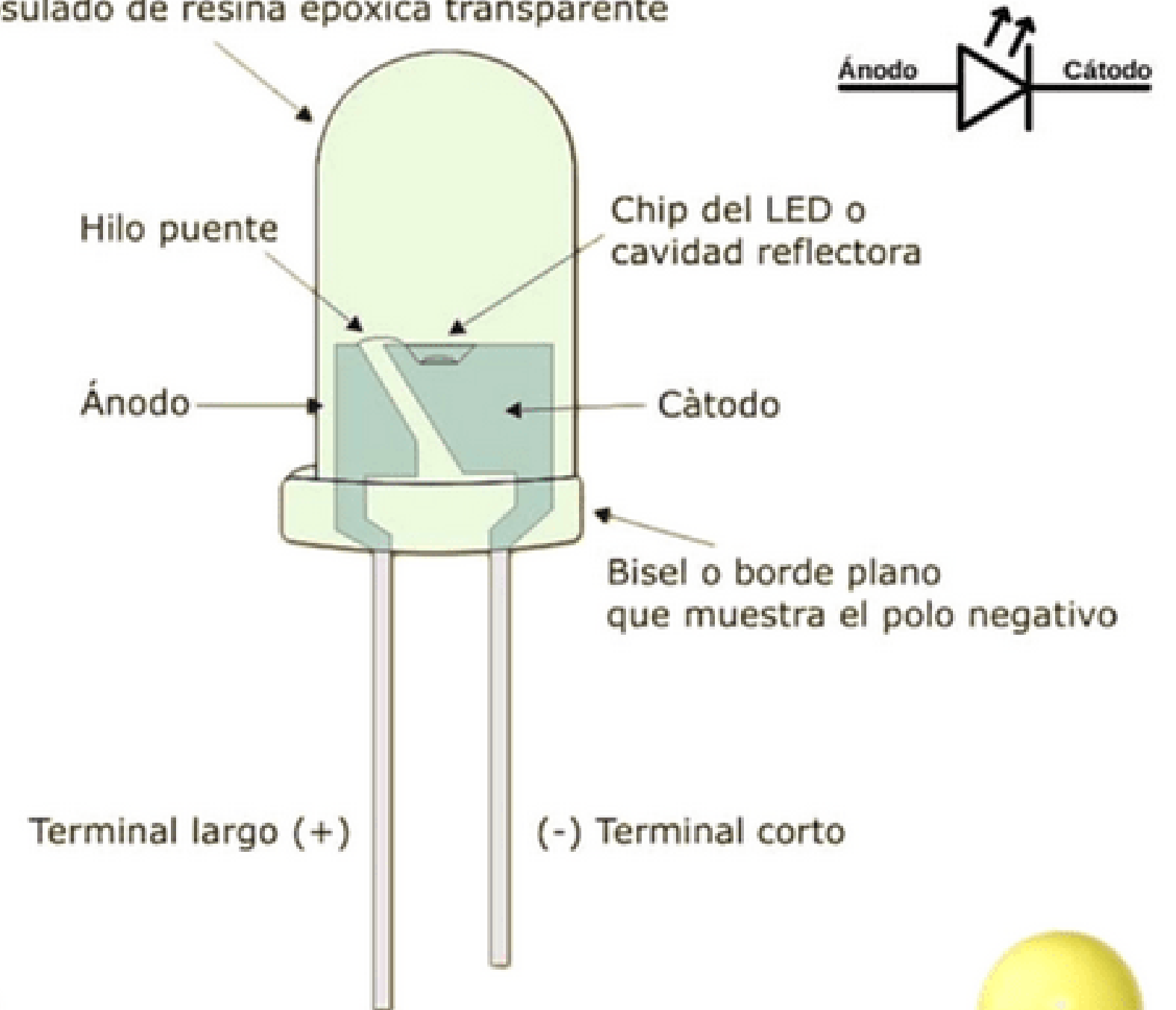




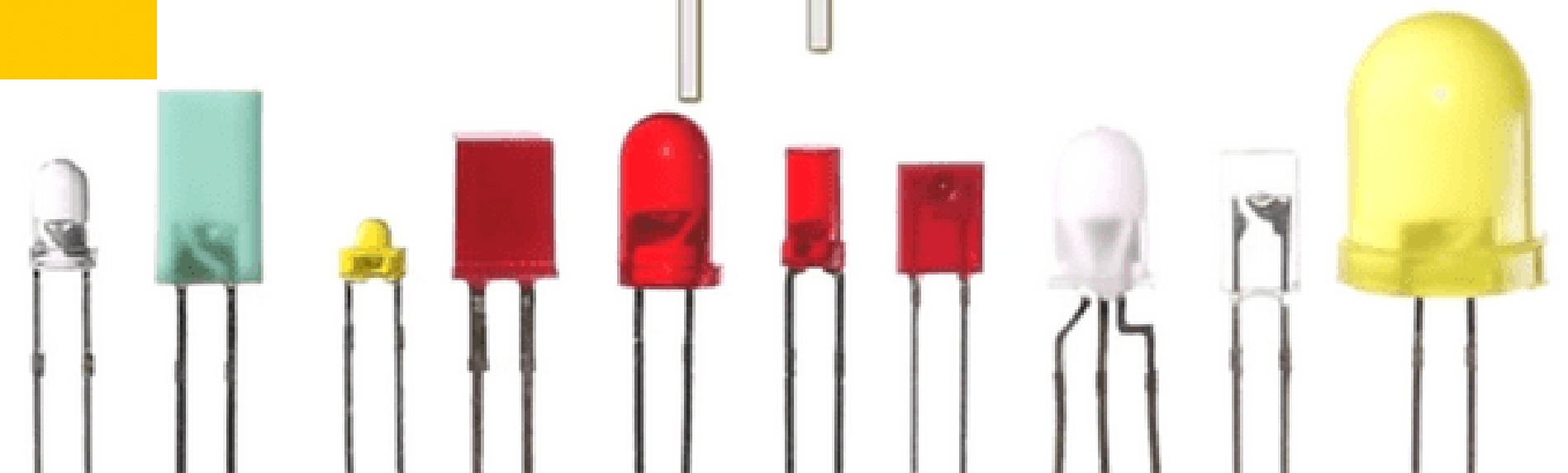
I/O pin con DIODO



Encapsulado de resina epòxica transparente

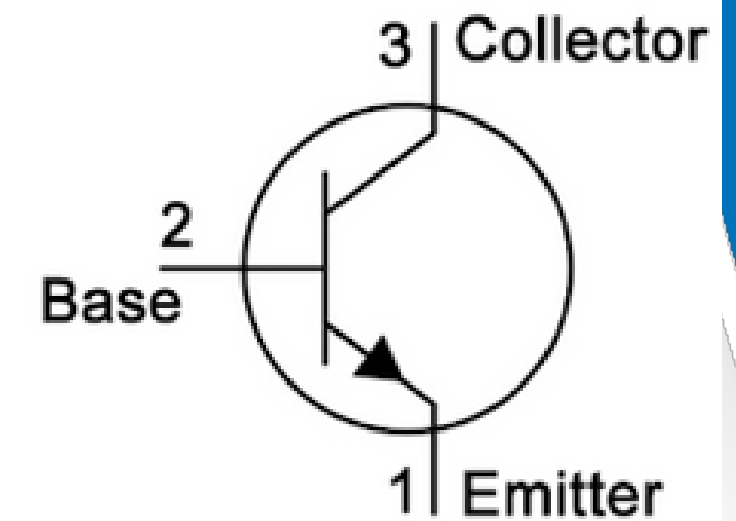
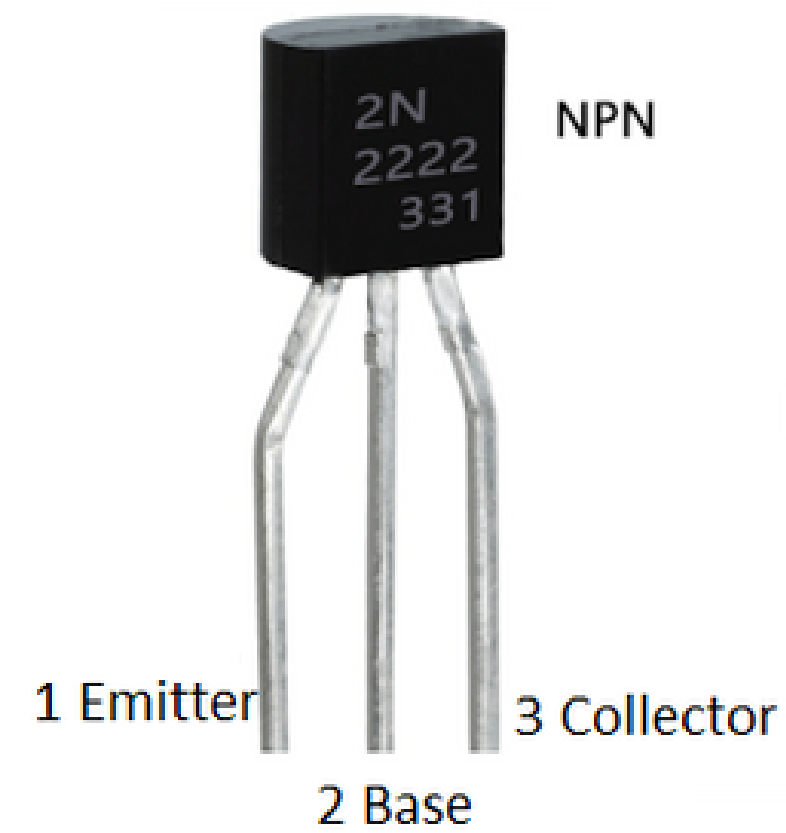
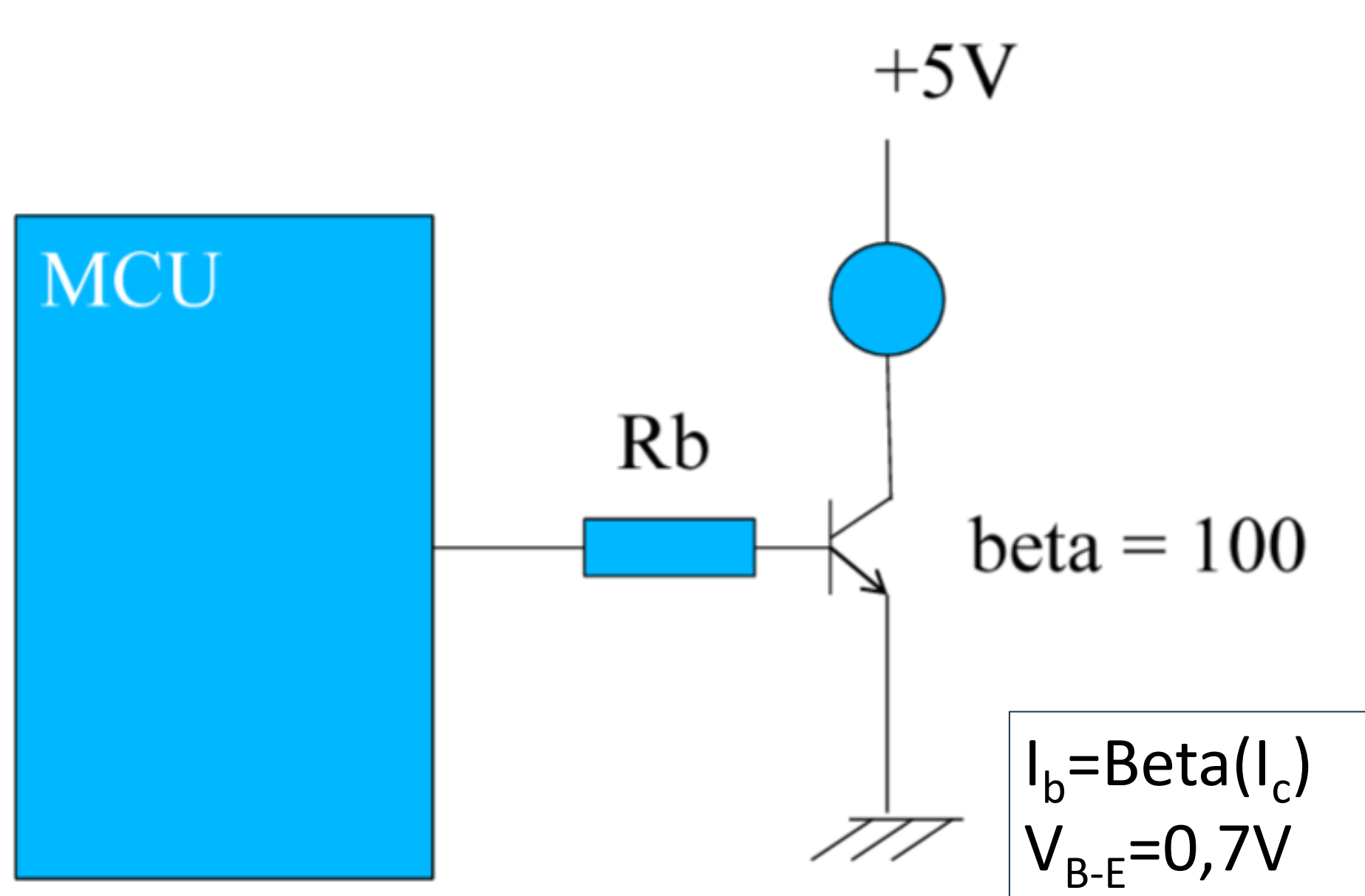


Corriente máxima por pin es 20 mA; recomendable 10mA y un total de consumo de todo el microcontrolador de 200mA





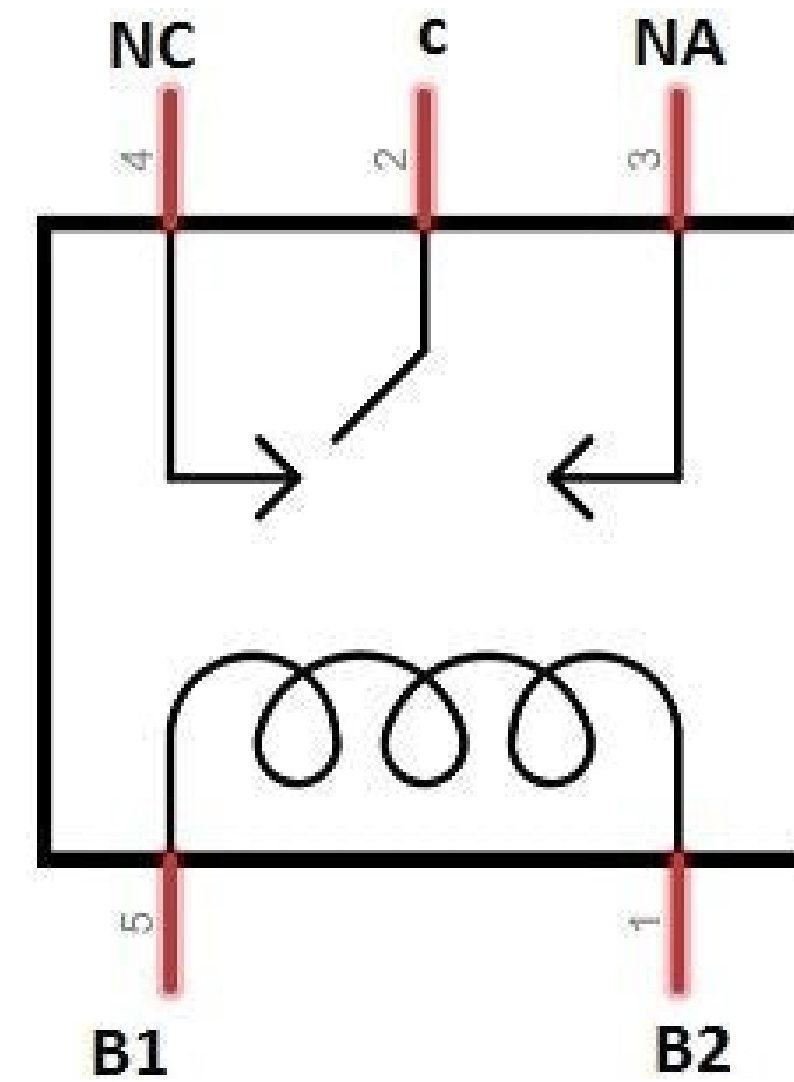
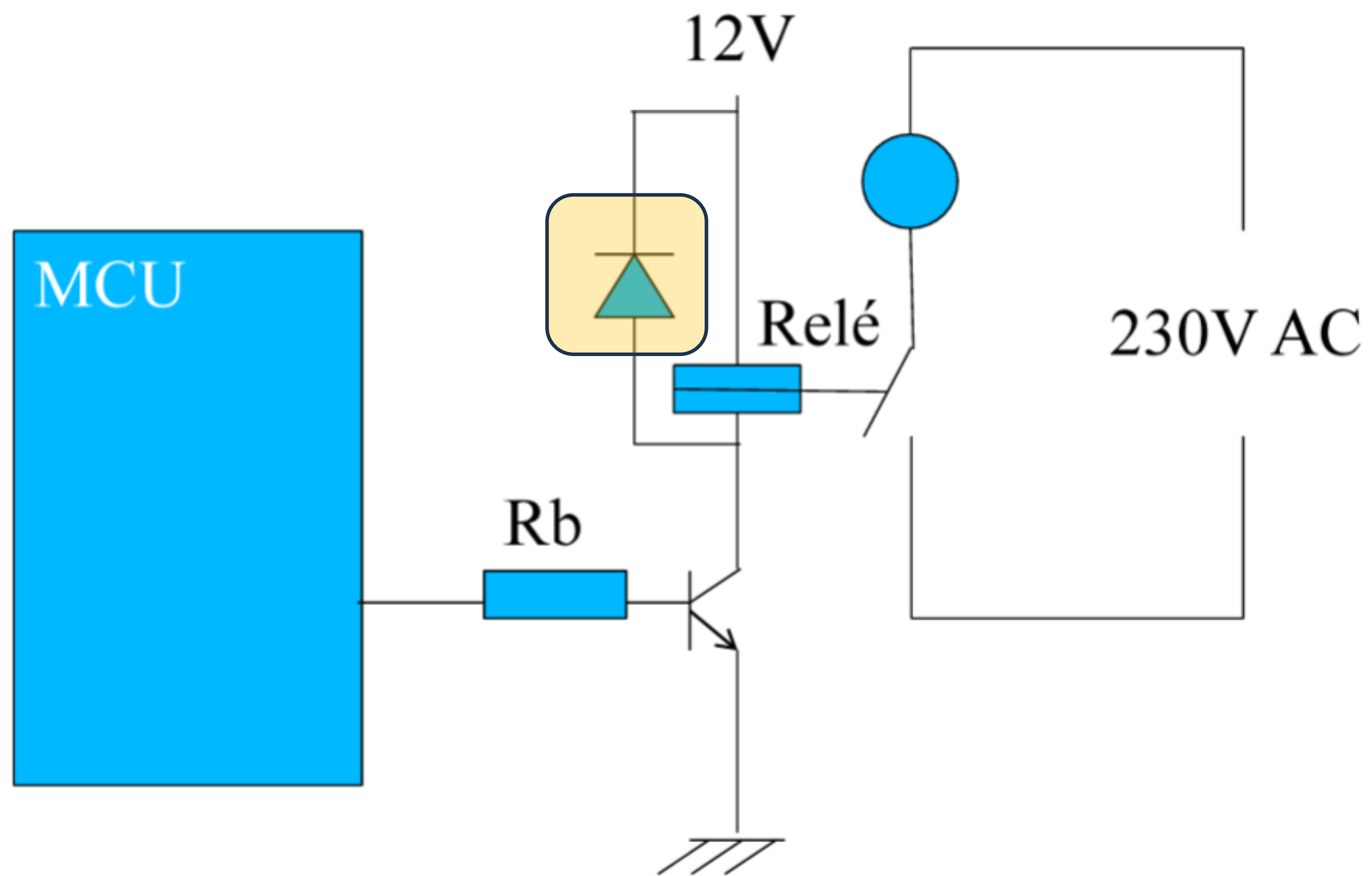
I/O pin con bombilla de 5v DC 0.75W



Beta = 100
 $V_{B-E} = 0,7V$
 $I_b > 1,5mA$

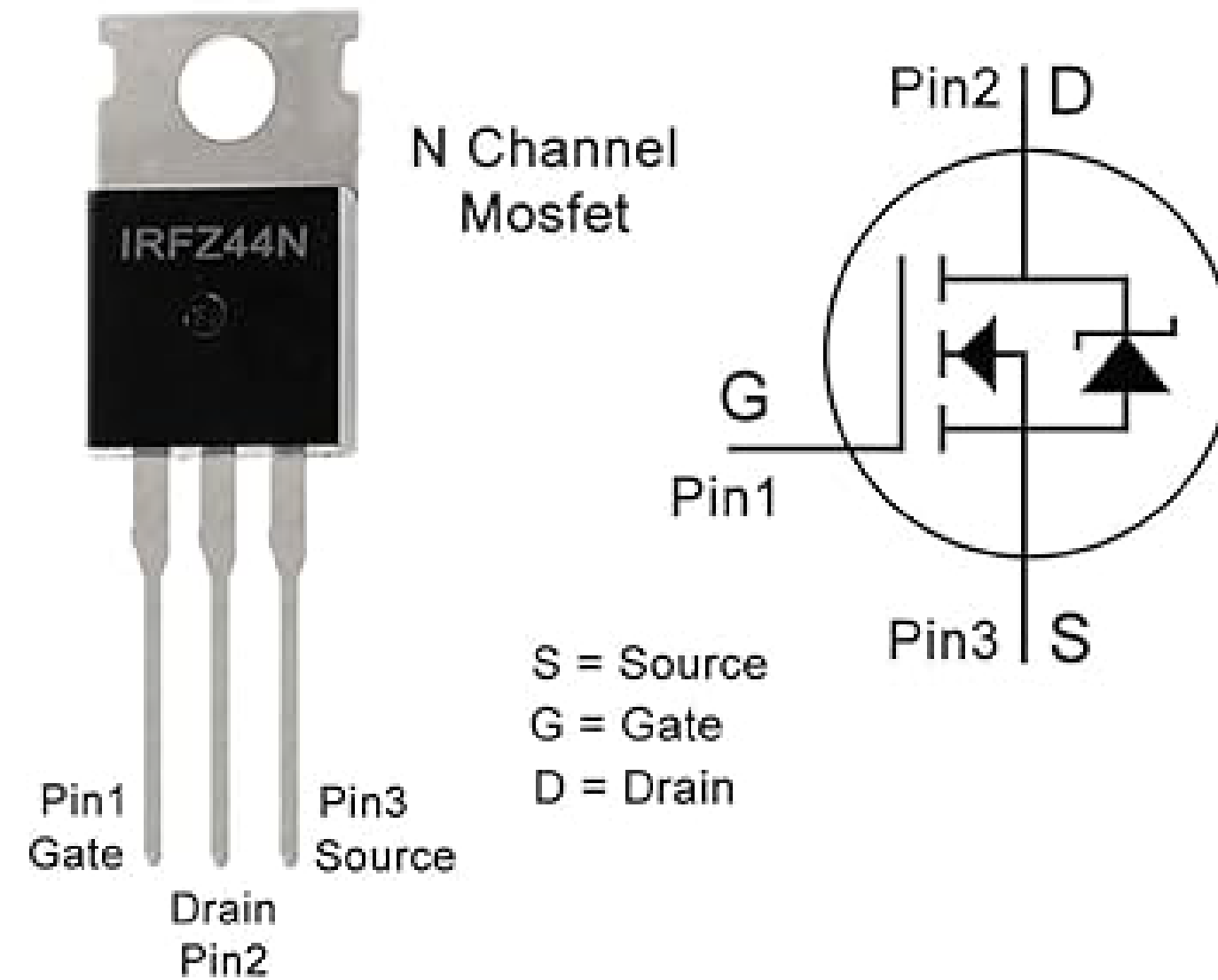
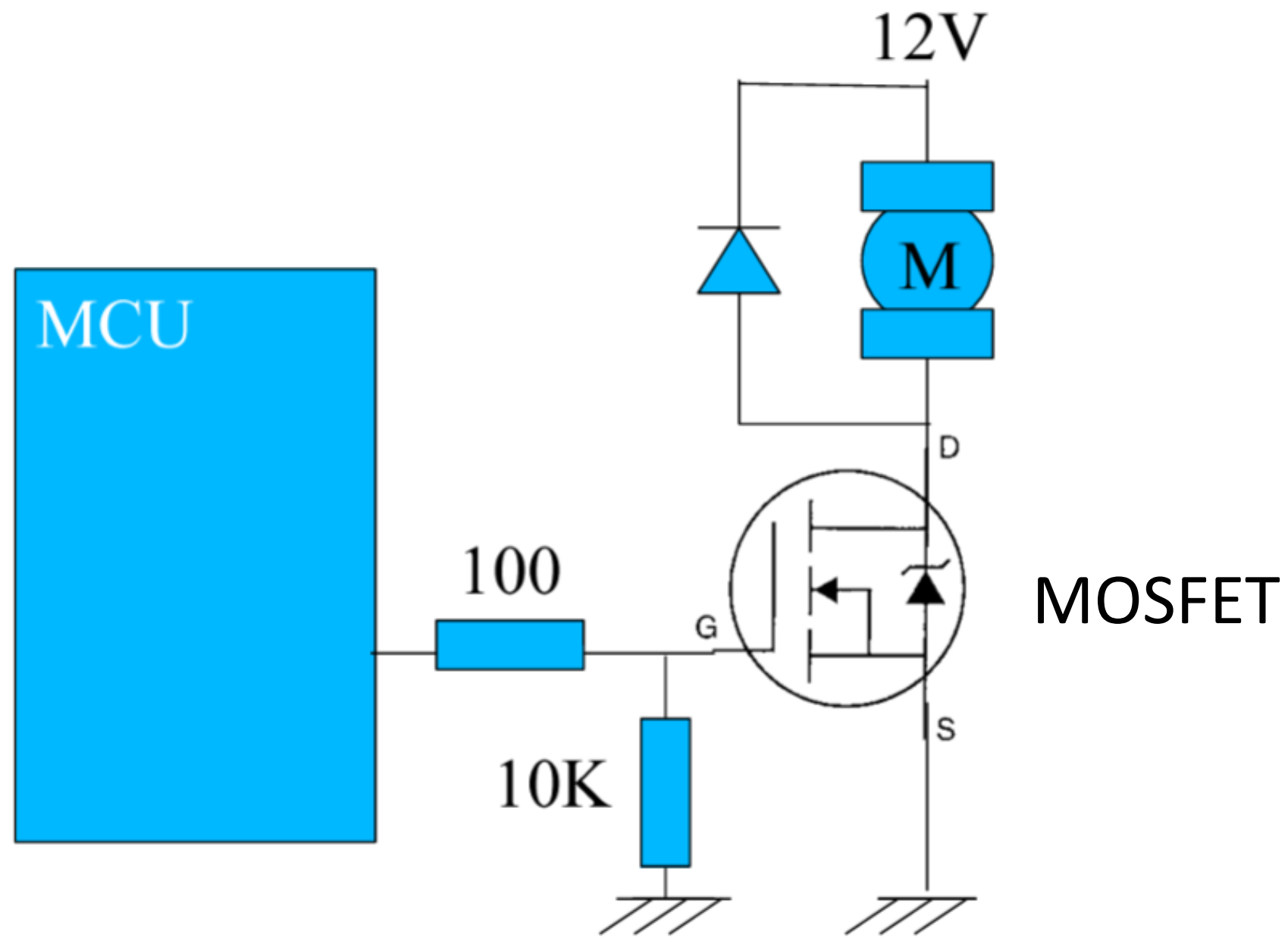


I/O pin con bombilla 230V AC 100 W





I/O pin con motor de 12V DC 50W

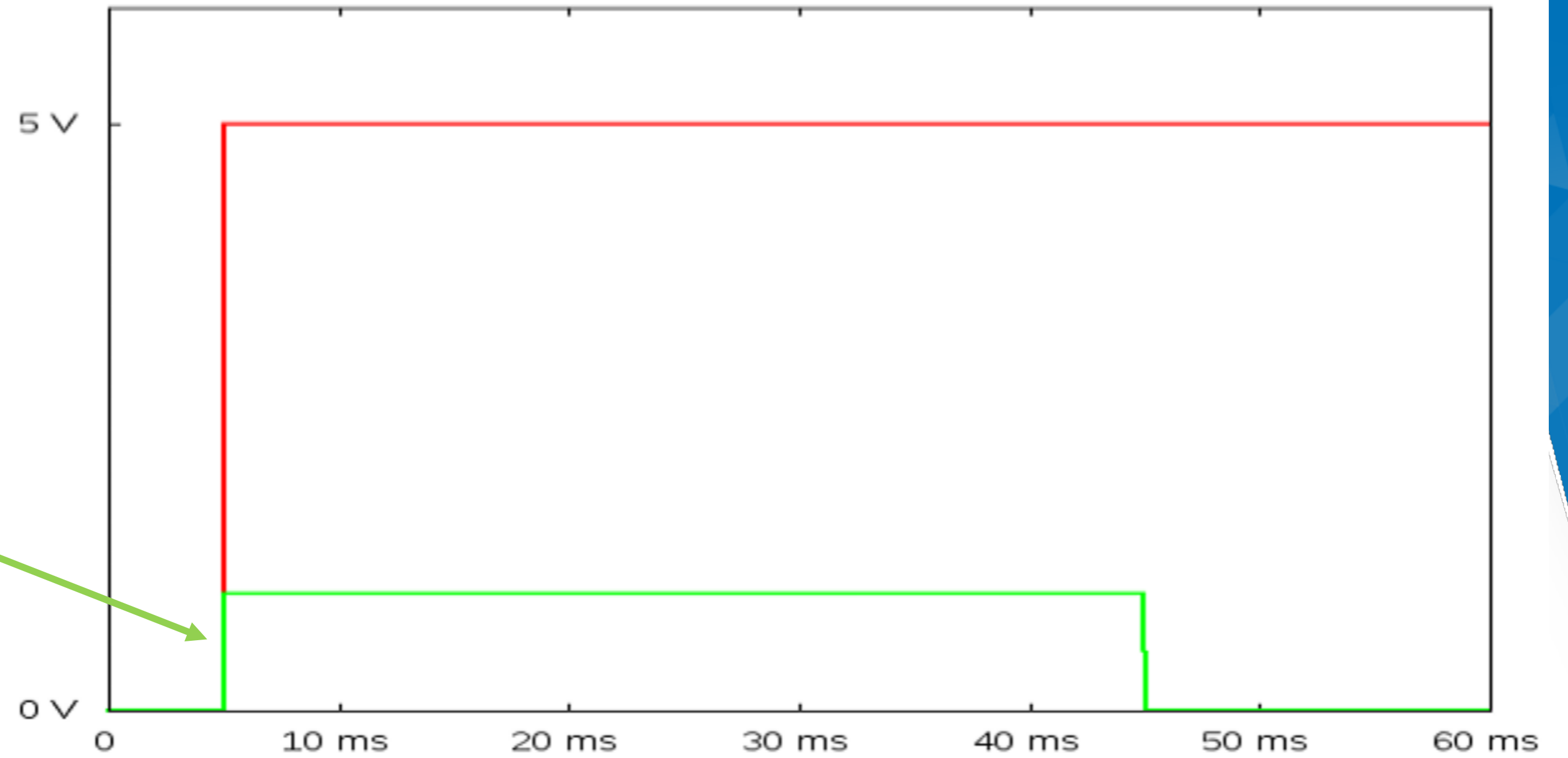
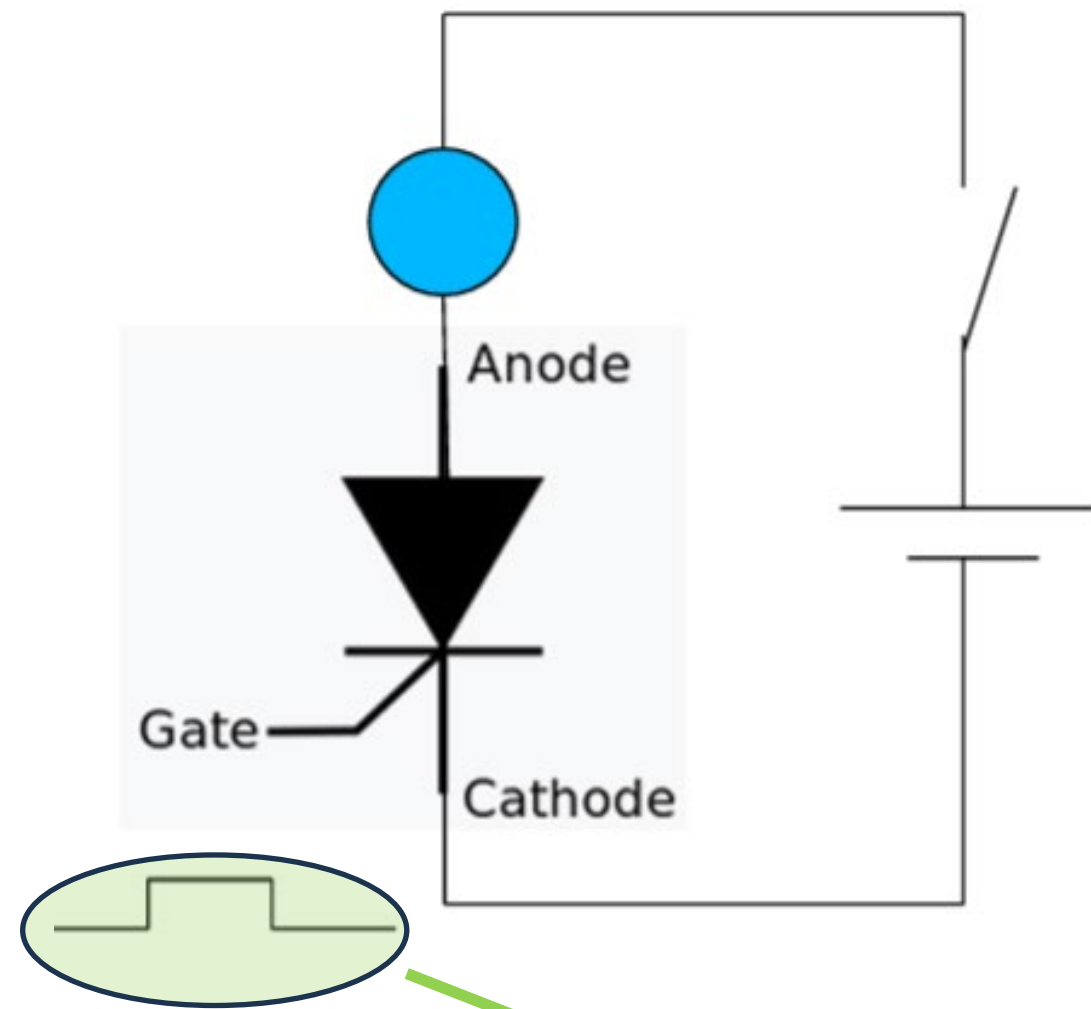


$$V_{ds} = 55 \text{ V}$$

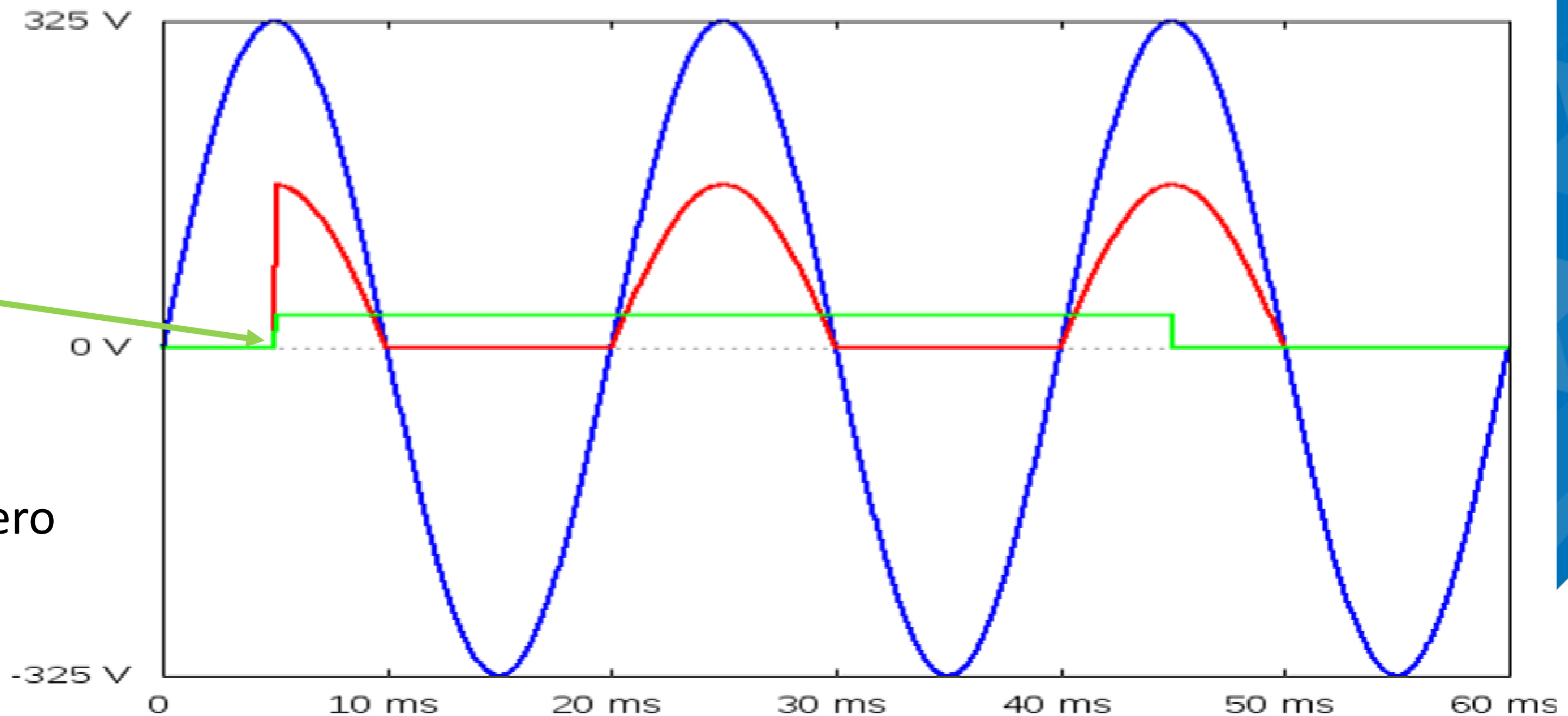
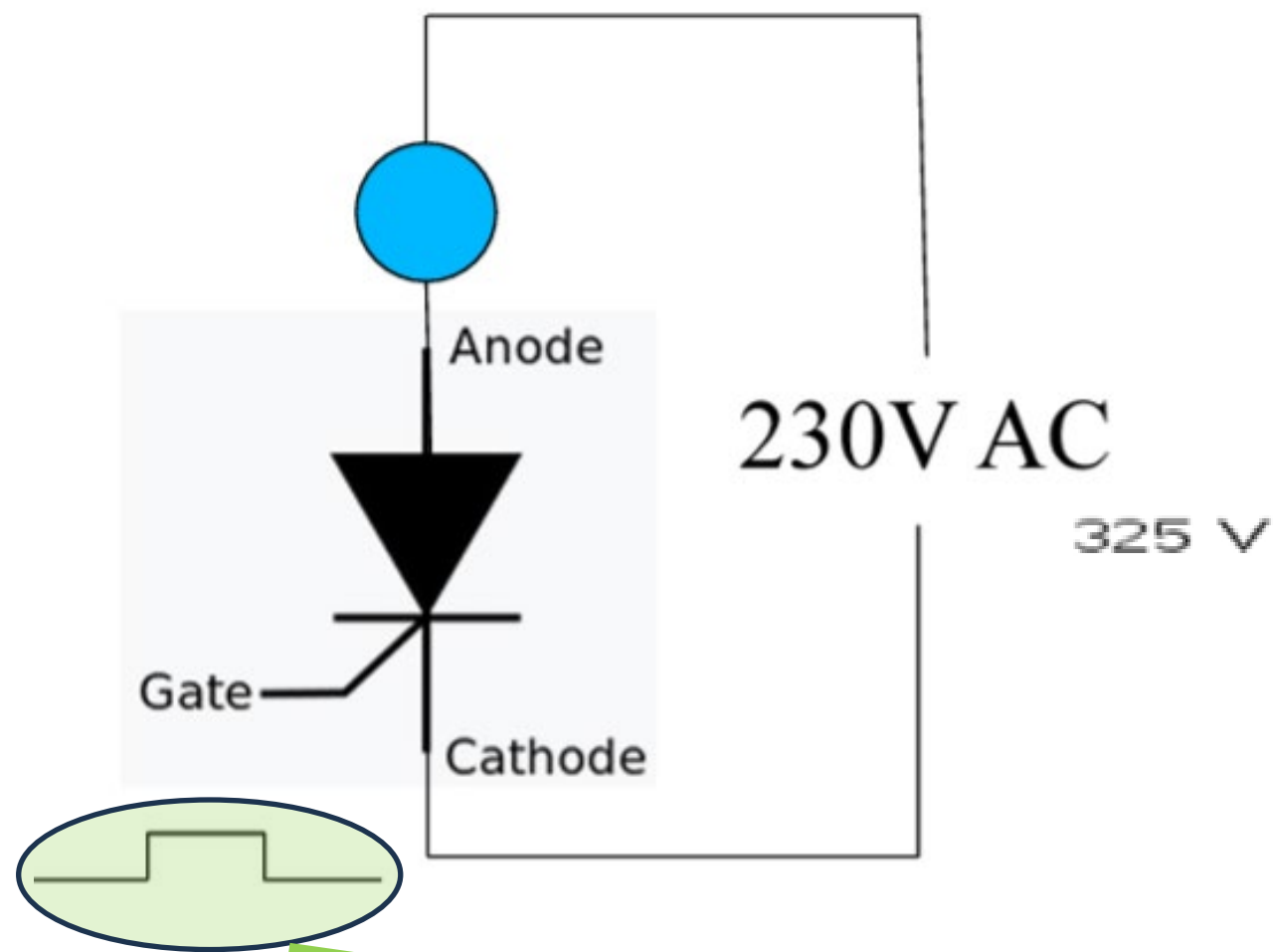
$$R_{ds} = 17,5 \text{ m}\Omega$$

$$I_d = 50 \text{ A}$$

Control de potencia con el tiristor: tiristor en DC

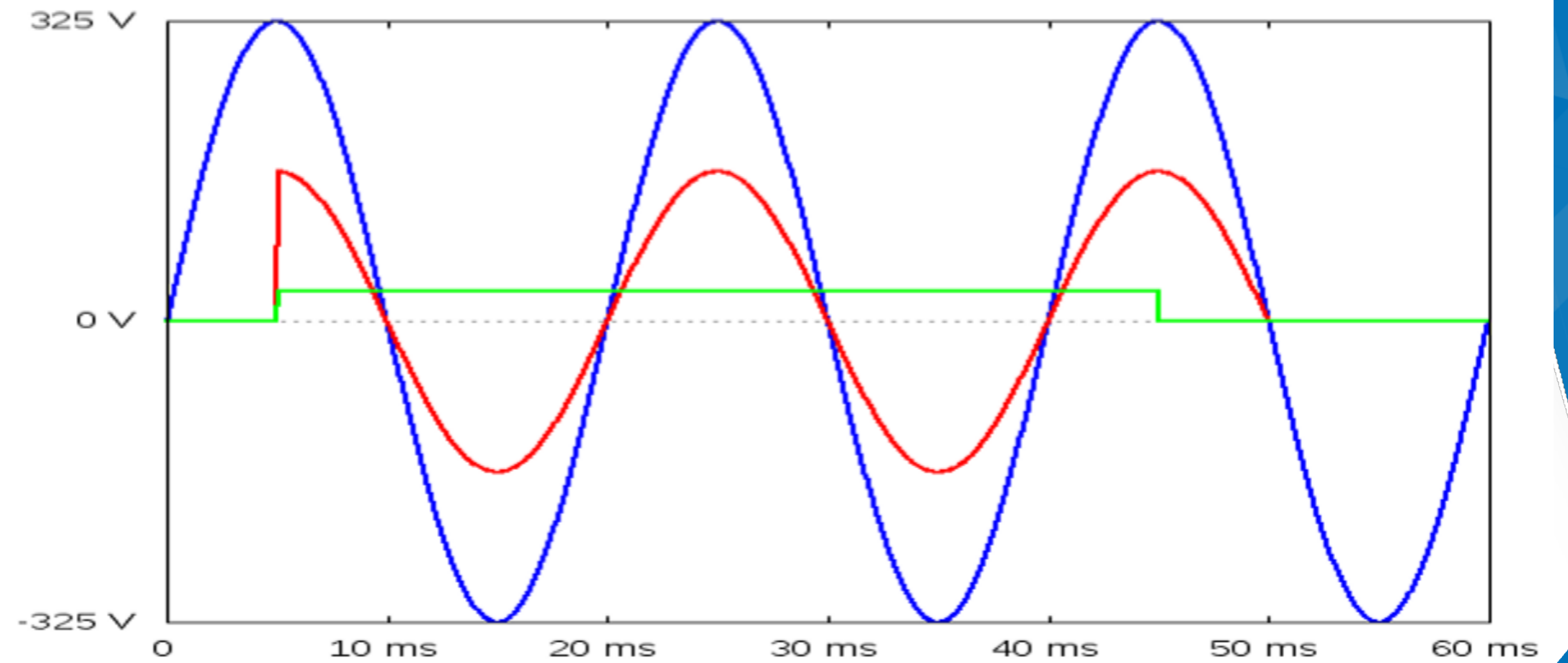
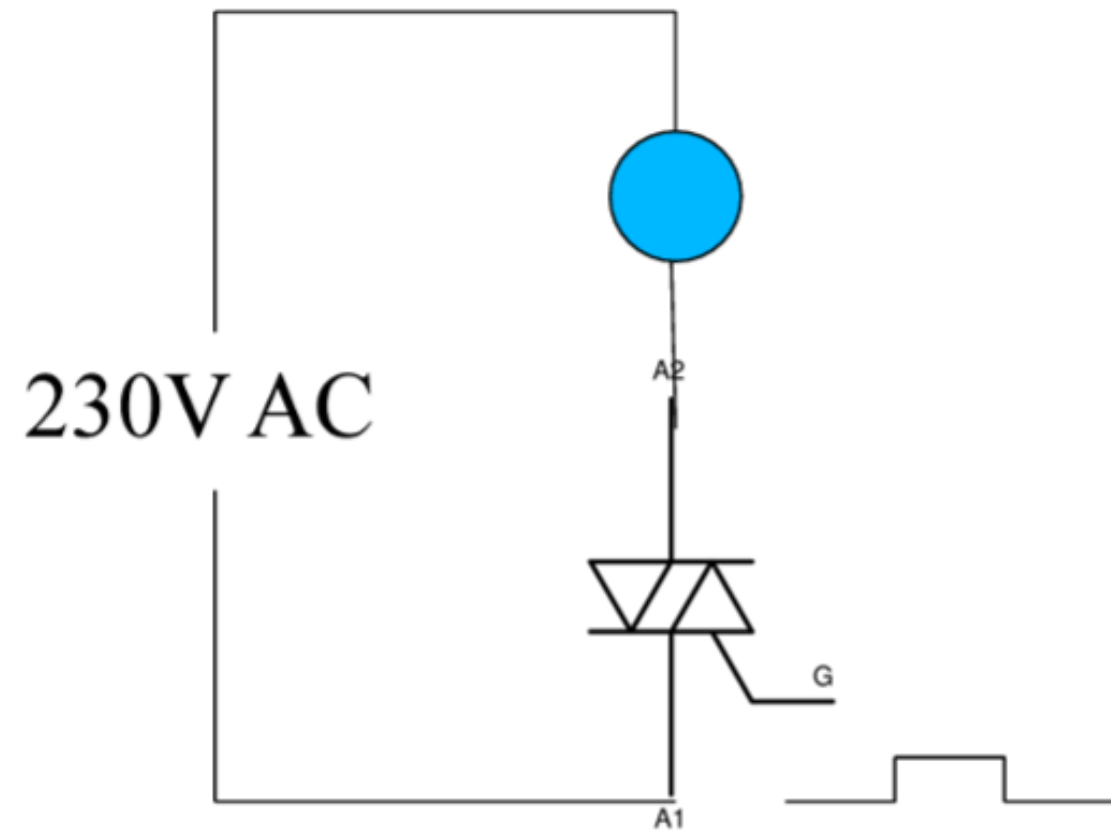


Control de potencia con el tiristor: tiristor en AC

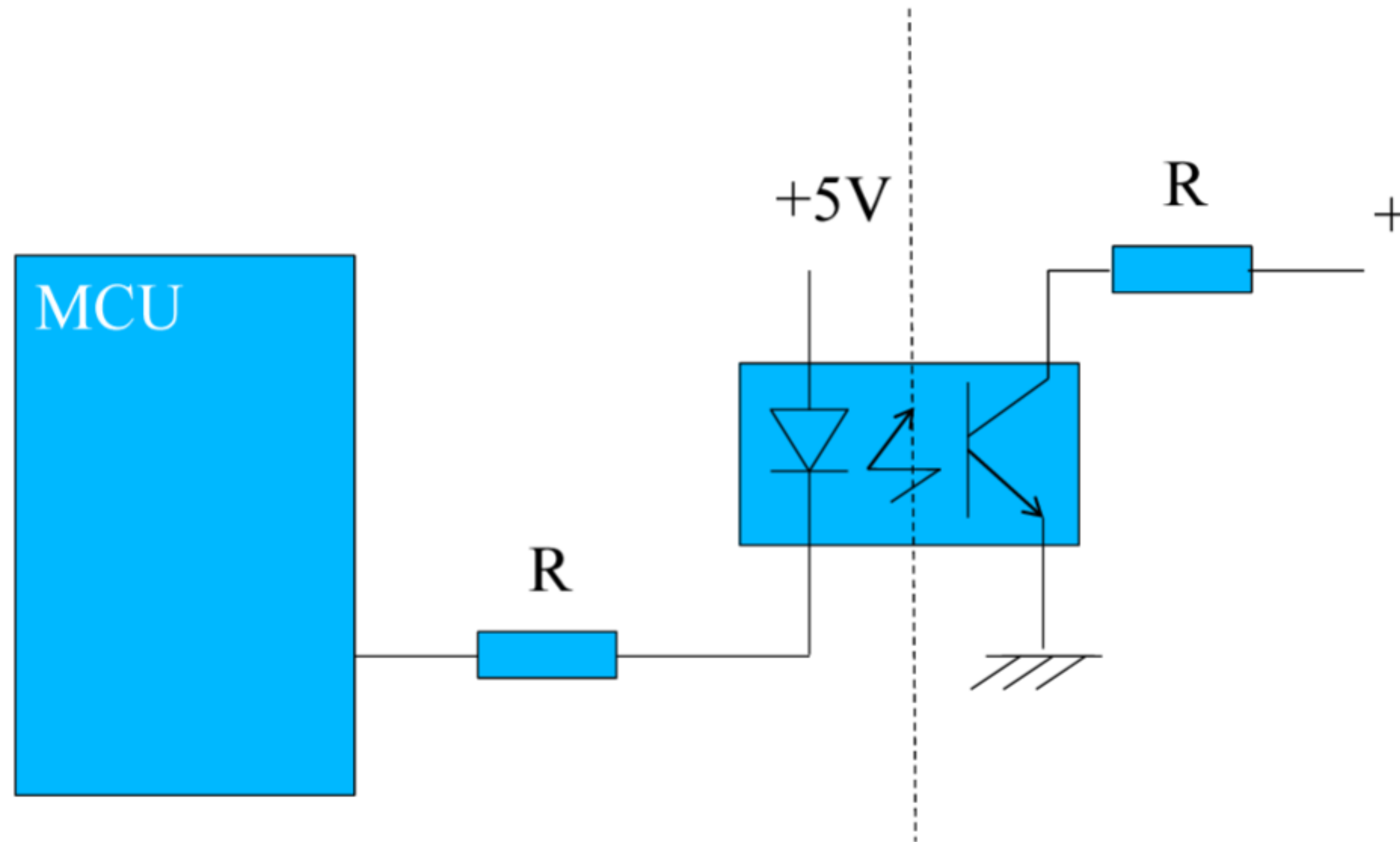


Conduce hasta cruce por cero

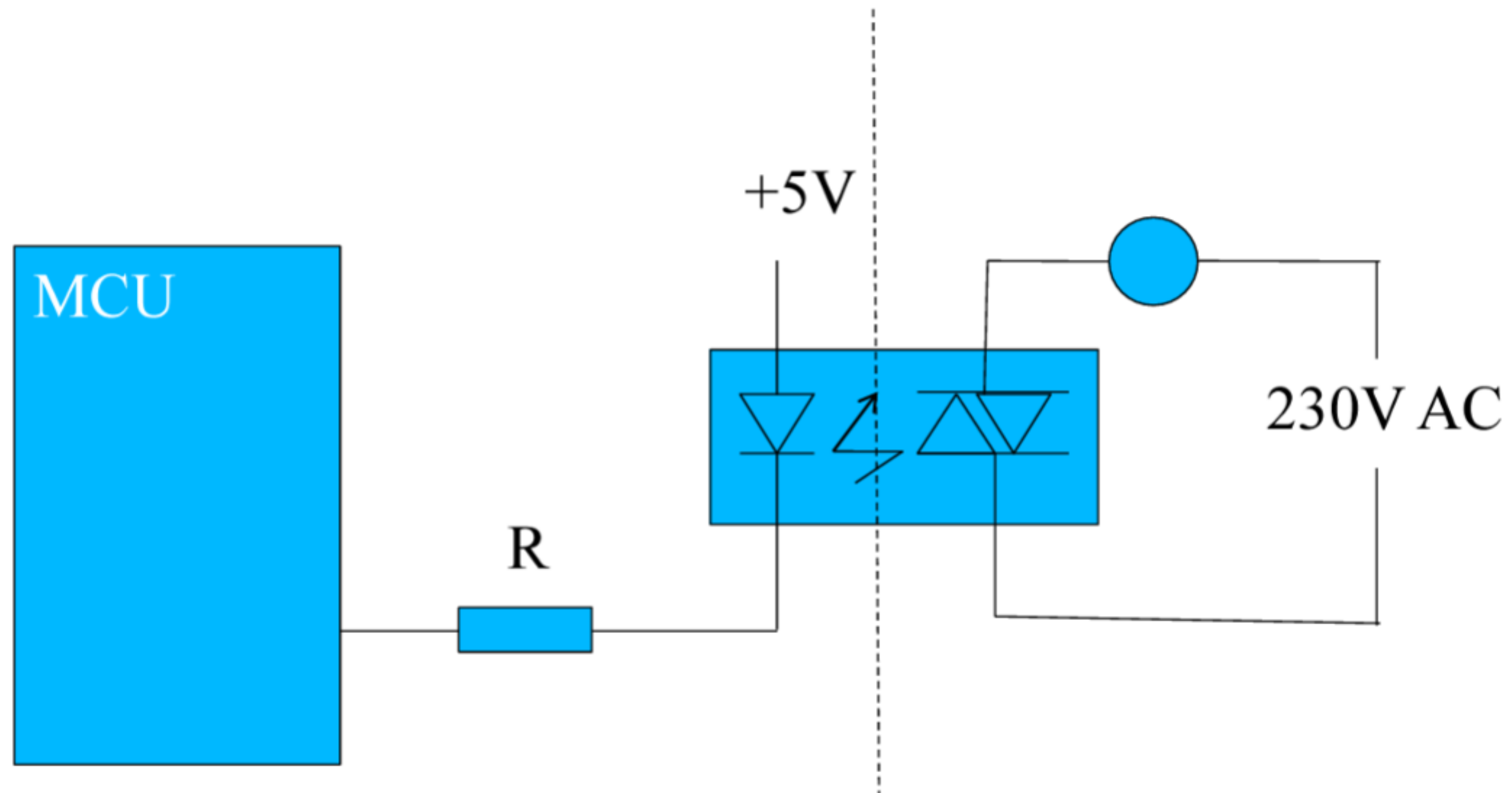
Control de potencia con TRIAC



Aislamiento mediante optoacoplador

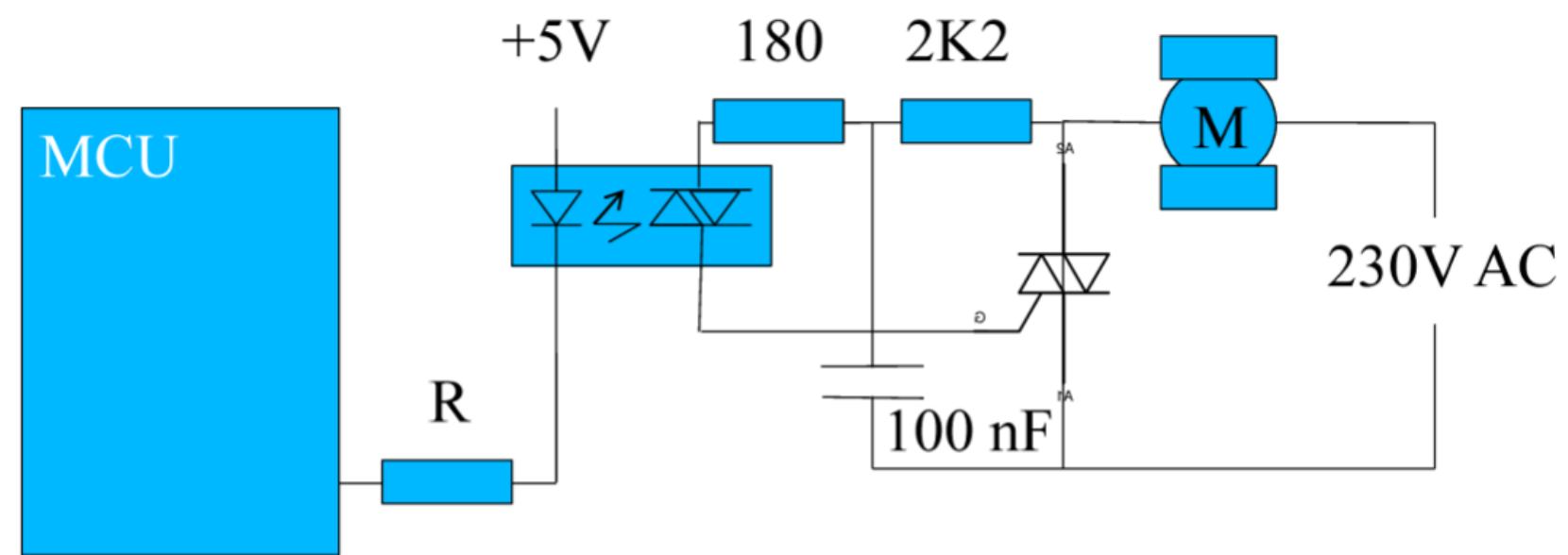


Aislamiento mediante Optotriac





Control de Potencia 230V AC con Optotriac y red SNUBBER



Circuito amortiguador de seguridad para el TRIAC, debido a una carga inductiva.

